

Global Nonexistence for Nonlinear Kirchhoff Systems

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Abstract

In this paper we consider the problem of non-continuation of solutions of dissipative nonlinear Kirchhoff systems, involving the $p(x)$ -Laplacian operator and governed by nonlinear driving forces $f = f(t, x, u)$, as well as nonlinear external damping terms $Q = Q(t, x, u, u_t)$, both of which could significantly dependent on the time t . The theorems are obtained through the study of the natural energy Eu associated to the solutions u of the systems. Thanks to a new approach of the classical potential well and concavity methods, we show the nonexistence of global solutions, when the initial energy is controlled above by a critical value; that is, when the initial data belong to a specific region in the phase plane. Several consequences, interesting in applications, are given in particular subcases. The results are original also for the scalar standard wave equation when $p \equiv 2$ and even for problems linearly damped.

1. Introduction

In this paper we investigate the question of global nonexistence of solutions for dissipative anisotropic nonhomogeneous $p(x)$ -Kirchhoff systems. As far as we know, this is the first non-continuation paper concerning with them; for related asymptotic stability problems we refer to [3]. The natural setting is the variable exponent Sobolev space $W_0^{1,p(\cdot)}(\Omega)$, where p varies continuously in Ω . In details, we consider in $\mathbb{R}_0^+ \times \Omega$

$$\begin{cases} u_{tt} - M(\mathcal{J}u(t)) \Delta_{p(x)}u + \mu|u|^{p(x)-2}u + Q(t, x, u, u_t) = f(t, x, u), \\ u(t, x) = 0 \end{cases} \quad \text{on } \mathbb{R}_0^+ \times \partial\Omega, \quad (1.1)$$

where $u = (u_1, \dots, u_N) = u(t, x)$ is the vectorial displacement, $N \geq 1$, $\mathbb{R}_0^+ = [0, \infty)$, Ω is a bounded domain of \mathbb{R}^n and $\mu \geq 0$. Here $\Delta_{p(x)}$ denotes the vectorial

$p(x)$ -Laplacian operator defined as $\operatorname{div}(|Du|^{p(x)-2}Du)$, where div is the vectorial divergence and Du the Jacobian matrix of u . While the associated $p(x)$ -Dirichlet energy integral is $\mathcal{I}u(t) = \int_{\Omega} \{|Du(t, x)|^{p(x)}/p(x)\} dx$. The functions f , M and Q represent a source force, a Kirchhoff dissipative term and an external damping term, respectively.

Throughout the paper, we assume that $(Q(t, x, u, v), v) \geq 0$ for all (t, x, u, v) in $\mathbb{R}_0^+ \times \Omega \times \mathbb{R}^N \times \mathbb{R}^N$,

$$Q \in C(\mathbb{R}_0^+ \times \Omega \times \mathbb{R}^N \times \mathbb{R}^N \rightarrow \mathbb{R}^N) \quad \text{and} \quad f \in C(\mathbb{R}_0^+ \times \Omega \times \mathbb{R}^N \rightarrow \mathbb{R}^N),$$

$$f(t, x, u) = F_u(t, x, u), \quad F(t, x, 0) = 0,$$

so that $F(t, x, u) = \int_0^1 (f(t, x, \tau u), u) d\tau$ is a potential for f in u ; and also (\mathcal{M}) the function $M \in C(\mathbb{R}_0^+ \rightarrow \mathbb{R}_0^+)$ is locally Lipschitz in \mathbb{R}^+ and such that

$$\gamma \mathcal{M}(\tau) \geq \tau M(\tau), \quad \tau \in \mathbb{R}_0^+, \quad \mathcal{M}(\tau) = \int_0^\tau M(z) dz,$$

for some number $\gamma \geq 1$.

The question of non-continuation of solutions is treated by means of the natural energy Eu associated with any solution u of the system, refer to (3.1). The main result is Theorem 3.1, where the initial energy $Eu(0)$ is bounded from above by the critical value \tilde{E}_1 ; see Fig. 1. Refining an argument introduced by PUCCI and SERRIN [22, Theorem 1–(ii)] for evolution systems with linear damping terms, together with a new combination of the classical potential well and concavity methods, in the way used, for example, in [17, 18, 23] for the wave case, and in [25] for the standard wave Kirchhoff equation, we completely extend the region of global nonexistence for the anisotropic Kirchhoff systems from Σ to $\tilde{\Sigma}$. Indeed, global nonexistence results are proved assuming only that $Eu(0) < \tilde{E}_1$, independently of the initial value $\|u(0, \cdot)\|_{q(\cdot)}$; as an illustrative example we refer to Corollary 4.1.

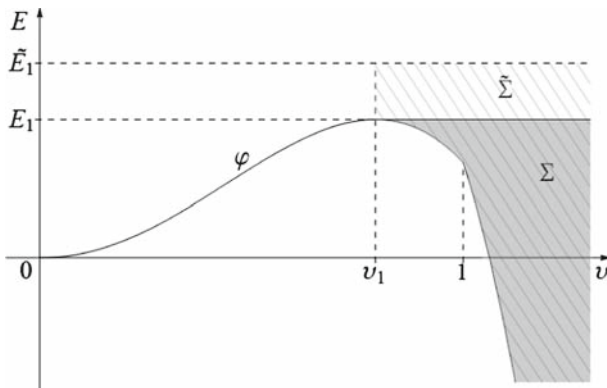


Fig. 1. The phase plane (v, E) . Here $E = Eu(0)$, where Eu represents the natural energy associated with the solution u of the system, while v stands for $\|u(0, \cdot)\|_{q(\cdot)}$. The global nonexistence results, given in [17, 18, 22–25] in special subcases of this paper, concern only the region Σ which is smaller than $\tilde{\Sigma}$, when global nonexistence occurs

Here $\|\cdot\|_{q(\cdot)}$ denotes the norm in the anisotropic Lebesgue space $L^{q(\cdot)}(\Omega)$, where $q(\cdot)$ is a variable exponent related to the growth of f in the u variable, see condition (\mathcal{F}_3) in Section 3, or the application given in the example (4.1)–(4.2). The results of this paper are new even in the standard wave case when $p \equiv 2$ as well as when Q is linear in the $v = u_t$ variable.

Several consequences are deduced in special subcases of f , M and Q , interesting in applications; see Section 4. We also show that if u is a global solution of (1.1) and $Eu(0) \leq E_1$, then $\tilde{E}_1 \leq E_1$. This result allows us to prove in a new way and wider setting that if u is a local solution of (1.1), with $\|u(0, \cdot)\|_{q(\cdot)} > v_1$ and $Eu(0) = E_1$, then u cannot be global, see Theorem 4.3. The possibility to cover this case was first discovered by VITILLARO [23], but with a different proof technique and only for strong solutions, even if not explicitly stated, refer to [23, the proof of case (a) of Theorem 3]. When f significantly depends on t , Theorem 4.3 handles also the case $Q \equiv 0$, not covered in [23], refer to Remark 4.1. Indeed, we are able to establish refined results, even dealing with a wider class of solutions verifying a weak conservation law, thanks to a new argument based on the lower bounds of the potential energy along a solution u . The main reason to consider weak solutions was first given in [20, Remark 4 at page 199]; see also [21, Remark 2 at page 49] and the discussion on [17, page 345].

In recent years, the study of p -Kirchhoff equations involving the quasilinear homogeneous p -Laplace operator, based on the theory of standard Sobolev spaces $W_0^{1,p}(\Omega)$, has been widely studied, see, for example, [6,25], while for wave equations [7], and for the elliptic case [5,8]. In particular, in [25] global nonexistence results are proved for scalar Kirchhoff equations, when $Eu(0) < E_1$ and all the exponents are constant, with $p(x) \equiv 2$. In addition, in [25] the conservation law is assumed only in the stronger form $(B)_s$, so that the energy function Eu is non-increasing in \mathbb{R}_0^+ (see Sections 3 and 4 for the definition of $(B)_s$ and Remark 5.1). Finally, in [25] the damping function Q depends only on v , while f is a pure power of u . Here we cover much more situations, in which the dependence on t could be significant.

Last but not least, we recall that the nonhomogeneous $p(x)$ -Kirchhoff operator has been used in the last decades to model various phenomena, see [9–16,19,26,27] and the references therein. Indeed, recently, there has been an increasing interest in studying systems involving somehow nonhomogeneous $p(x)$ -Laplace operators, motivated by the image restoration problem, by the modeling of electro-rheological fluids (sometimes referred to as *smart fluids*), as well as the thermo-convective flows of non-Newtonian fluids: details and further references can be found in [2 and 19], while for the regularity of weak solutions we refer to [1].

2. Basic facts and notation

Let $h \in C_+(\overline{\Omega})$, where

$$C_+(\overline{\Omega}) = \{h \in C(\overline{\Omega}) : \min_{x \in \overline{\Omega}} h(x) > 1\},$$

and define

$$h_+ = \sup_{x \in \Omega} h(x) \quad \text{and} \quad h_- = \inf_{x \in \Omega} h(x).$$

Hereafter $p \in C_+(\overline{\Omega})$ is fixed. The *variable exponent Lebesgue space*, denoted by $L^{p(\cdot)}(\Omega) = [L^{p(\cdot)}(\Omega)]^N$ and consisting of all the measurable vector-valued functions $u : \Omega \rightarrow \mathbb{R}^N$ such that $\int_{\Omega} |u(x)|^{p(x)} dx$ is finite, is endowed with the so called *Luxemburg norm*

$$\|u\|_{p(\cdot)} = \inf \left\{ \lambda > 0 : \int_{\Omega} \left| \frac{u(x)}{\lambda} \right|^{p(x)} dx \leq 1 \right\},$$

and is a separable and reflexive Banach space, refer to [16, Corollaries 2.12 and 2.7]. For basic properties of the variable exponent Lebesgue spaces we refer to [16]. Since here $0 < |\Omega| < \infty$, if $q \in C_+(\overline{\Omega})$ and $p \leq q$ in Ω , then the embedding $L^{q(\cdot)}(\Omega) \hookrightarrow L^{p(\cdot)}(\Omega)$ is continuous, refer to [16, Theorem 2.8].

Let $L^{p'(\cdot)}(\Omega)$ be the conjugate space of $L^{p(\cdot)}(\Omega)$, obtained by conjugating the exponent pointwise that is, $1/p(x) + 1/p'(x) = 1$, [10, Theorem 1.14]. For any $u \in L^{p(\cdot)}(\Omega)$ and $v \in L^{p'(\cdot)}(\Omega)$ the following Hölder type inequality

$$\left| \int_{\Omega} (u(x), v(x)) dx \right| \leq \left(\frac{1}{p_-} + \frac{1}{p'_-} \right) \|u\|_{p(\cdot)} \|v\|_{p'(\cdot)}$$

is valid, where (\cdot, \cdot) is the inner product on $\mathbb{R}^N \times \mathbb{R}^N$, [16, Theorem 2.1].

An important role in manipulating the generalized Lebesgue–Sobolev spaces is played by the $p(\cdot)$ -*modular* of the $L^{p(\cdot)}(\Omega)$ space, which is the convex function $\rho_{p(\cdot)} : L^{p(\cdot)}(\Omega) \rightarrow \mathbb{R}$ defined by

$$\rho_{p(\cdot)}(u) = \int_{\Omega} |u(x)|^{p(x)} dx.$$

If $(u_j)_j, u \in L^{p(\cdot)}(\Omega)$, then the following relations hold: $\|u\|_{p(\cdot)} < 1$ ($= 1; > 1$) $\Leftrightarrow \rho_{p(\cdot)}(u) < 1$ ($= 1; > 1$),

$$\begin{aligned} \|u\|_{p(\cdot)} \geq 1 &\Rightarrow \|u\|_{p(\cdot)}^{p_-} \leq \rho_{p(\cdot)}(u) \leq \|u\|_{p(\cdot)}^{p_+}, \\ \|u\|_{p(\cdot)} \leq 1 &\Rightarrow \|u\|_{p(\cdot)}^{p_+} \leq \rho_{p(\cdot)}(u) \leq \|u\|_{p(\cdot)}^{p_-}, \end{aligned} \tag{2.1}$$

and $\|u_j - u\|_{p(\cdot)} \rightarrow 0 \Leftrightarrow \rho_{p(\cdot)}(u_j - u) \rightarrow 0 \Leftrightarrow (u_j)_j$ converges to u in measure in Ω and $\rho_{p(\cdot)}(u_j) \rightarrow \rho_{p(\cdot)}(u)$, since $p_+ < \infty$. In particular, $\rho_{p(\cdot)}$ is continuous in $L^{p(\cdot)}(\Omega)$. For a proof of these facts see [10, Theorem 1.4] and [16].

The *variable exponent Sobolev space* $W^{1,p(\cdot)}(\Omega) = [W^{1,p(\cdot)}(\Omega)]^N$, consisting of functions $u \in L^{p(\cdot)}(\Omega)$ whose distributional Jacobian matrix Du is in $[L^{p(\cdot)}(\Omega)]^{nN}$, is endowed with the norm

$$\|u\|_{1,p(\cdot)} = \|u\|_{p(\cdot)} + \|Du\|_{p(\cdot)}.$$

Thus $W^{1,p(\cdot)}(\Omega)$ is a separable and reflexive Banach space, refer to [16, Theorem 3.1]. Define $H_0^{1,p(\cdot)}(\Omega) = [H_0^{1,p(\cdot)}(\Omega)]^N$ as the closure of $C_0^\infty(\Omega) = [C_0^\infty(\Omega)]^N$

in $W^{1,p(\cdot)}(\Omega)$, and $W_0^{1,p(\cdot)}(\Omega) = [W_0^{1,p(\cdot)}(\Omega)]^N$ as the Sobolev space of the functions $u \in W^{1,p(\cdot)}(\Omega)$, with zero boundary values, refer to [12]. As shown by ЗНИКОВ [26,27], the smooth functions are in general not dense in $W^{1,p(\cdot)}(\Omega)$, but if $p \in C_+(\overline{\Omega})$ is logarithmic Hölder continuous, that is, there exists $L > 0$ such that for all $x, y \in \Omega$, with $0 < |x - y| \leq 1/2$

$$|p(x) - p(y)| \leq -\frac{L}{\log(|x - y|)}, \tag{2.2}$$

then $H_0^{1,p(\cdot)}(\Omega) = W_0^{1,p(\cdot)}(\Omega)$, namely the density property holds, see [12,15] and in particular [14, Theorem 3.3]. Since Ω is a bounded domain, if $p \in C_+(\overline{\Omega})$ satisfies (2.2), then the $p(\cdot)$ -Poincaré inequality

$$\|u\|_{p(\cdot)} \leq C \|Du\|_{p(\cdot)}$$

is valid for all $u \in W_0^{1,p(\cdot)}(\Omega)$, where C depends on $p, |\Omega|, \text{diam}(\Omega), n$ and N , [14, Theorem 4.1], and so

$$\|u\| = \|Du\|_{p(\cdot)},$$

is an equivalent norm in $W_0^{1,p(\cdot)}(\Omega)$. Moreover $W_0^{1,p(\cdot)}(\Omega)$ is a separable and reflexive Banach space. If $p_+ < n$ and (2.2) holds, then the embedding $W_0^{1,p(\cdot)}(\Omega) \hookrightarrow L^{p^*(\cdot)}(\Omega)$ is continuous, see [13, Theorem 1.1], where p^* is the critical variable exponent related to p , defined by the relation

$$p^*(x) = \frac{np(x)}{n - p(x)} \text{ for all } x \in \Omega.$$

Details, extensions and further references can be found in [10, 12–16].

Hereafter, we assume that

$$p \in C_+(\overline{\Omega}) \text{ satisfies (2.2) and } 1 < p_- \leq p_+ < n.$$

For all $h \in C(\overline{\Omega})$, with $1 \leq h \leq p^*$ in Ω , we denote by $\lambda_{h(\cdot)}$ the Sobolev constant, depending on $h, p, |\Omega|, n$ and N , of the continuous embedding $W_0^{1,p(\cdot)}(\Omega) \hookrightarrow L^{h(\cdot)}(\Omega)$, that is

$$\|u\|_{h(\cdot)} \leq \lambda_{h(\cdot)} \|Du\|_{p(\cdot)} \text{ for all } u \in W_0^{1,p(\cdot)}(\Omega), \tag{2.3}$$

see [13, Theorem 1.1] and also [16, Theorem 2.8]. Of course in (2.3) we can take $h \equiv 1$.

For simplicity in notation

$$L^{p(\cdot)}(\Omega) = [L^{p(\cdot)}(\Omega)]^N, \quad W_0^{1,p(\cdot)}(\Omega) = [W_0^{1,p(\cdot)}(\Omega)]^N,$$

endowed with the norms $\|\cdot\|_{p(\cdot)}$ and $\|u\| = \|Du\|_{p(\cdot)}$, respectively.

Throughout the paper, the usual Lebesgue space $L^2(\Omega) = [L^2(\Omega)]^N$ is equipped with the canonical norm $\|\varphi\|_2 = (\int_{\Omega} |\varphi(x)|^2 dx)^{1/2}$, while the elementary bracket pairing $\langle \varphi, \psi \rangle = \int_{\Omega} \varphi(x) \psi(x) dx$ is clearly well defined for all φ, ψ such that $(\varphi, \psi) \in L^1(\Omega)$. Finally

$$K = C(\mathbb{R}_0^+ \rightarrow W_0^{1,p(\cdot)}(\Omega)) \cap C^1(\mathbb{R}_0^+ \rightarrow L^2(\Omega))$$

denotes the main solution and test function space, adopted in Sections 3 and 4.

3. The main theorem

In this section we provide a non-continuation result for the solutions of the problem (1.1) and assume that f , M and Q are as in the Section 1. Suppose also that for all $\phi \in K$

$$(\mathcal{F}_1) \quad \begin{aligned} F(t, \cdot, \phi(t, \cdot)), (f(t, \cdot, \phi(t, \cdot)), \phi(t, \cdot)) &\in L^1(\Omega) \text{ for all } t \in \mathbb{R}_0^+; \\ \langle f(t, \cdot, \phi(t, \cdot)), \phi(t, \cdot) \rangle &\in L^1_{\text{loc}}(\mathbb{R}_0^+). \end{aligned}$$

The potential energy of the field $\phi \in K$ is given by

$$\mathcal{F}\phi(t) = \mathcal{F}(t, \phi) = \int_{\Omega} F(t, x, \phi(t, x)) \, dx,$$

and it is well defined by (\mathcal{F}_1) , while the natural total energy of the field $\phi \in K$, associated with the problem (1.1), is

$$\begin{aligned} E\phi(t) &= \frac{1}{2} \|\phi_t(t, \cdot)\|_2^2 + \mathcal{A}\phi(t) - \mathcal{F}\phi(t), \\ \mathcal{A}\phi(t) &= \mathcal{M}(\mathcal{I}\phi(t)) + \mu \int_{\Omega} \frac{|\phi(t, x)|^{p(x)}}{p(x)} \, dx \geq 0, \end{aligned} \tag{3.1}$$

where $\mu \geq 0$ and $\mathcal{I}\phi$ is the $p(\cdot)$ -Dirichlet energy integral, that is

$$\mathcal{I}\phi(t) = \mathcal{I}(t, \phi) = \int_{\Omega} \frac{|D\phi(t, x)|^{p(x)}}{p(x)} \, dx.$$

Of course $E\phi$ is well defined in K . For all $\phi \in K$ and $(t, x) \in \mathbb{R}_0^+ \times \Omega$ we define pointwise

$$A\phi(t, x) = -M(\mathcal{I}\phi(t))\Delta_{p(x)}\phi(t, x) + \mu|\phi(t, x)|^{p(x)-2}\phi(t, x), \tag{3.2}$$

so that A is the Fréchet derivative of \mathcal{A} with respect to ϕ . By (\mathcal{M}) we have

$$\begin{aligned} \langle A\phi(t, \cdot), \phi(t, \cdot) \rangle &= M(\mathcal{I}\phi(t))\rho_{p(\cdot)}(D\phi(t, \cdot)) + \mu\rho_{p(\cdot)}(\phi(t, \cdot)) \\ &\leq p_+ \left\{ \mathcal{I}\phi(t)M(\mathcal{I}\phi(t)) + \mu \int_{\Omega} \frac{|\phi(t, x)|^{p(x)}}{p(x)} \, dx \right\} \\ &\leq \gamma p_+ \mathcal{A}\phi(t). \end{aligned} \tag{3.3}$$

Before introducing the definition of the solution to (1.1), we assume the following monotonicity condition

$$(\mathcal{F}_2) \quad \mathcal{F}_t \geq 0 \text{ in } \mathbb{R}_0^+ \times W_0^{1,p(\cdot)}(\Omega),$$

where \mathcal{F}_t is the partial derivative with respect to t of $\mathcal{F} = \mathcal{F}(t, w)$, with $(t, w) \in \mathbb{R}_0^+ \times W_0^{1,p(\cdot)}(\Omega)$.

Following [3 and 20], we say that u is a (weak) solution of (1.1) if $u \in K$ satisfies the two properties:

(A) *Distribution Identity*

$$\begin{aligned} \langle u_t, \phi \rangle \Big|_0^t &= \int_0^t \{ \langle u_t, \phi_t \rangle - M(\mathcal{I}u(\tau)) \cdot \langle |Du|^{p(\cdot)-2} Du, D\phi \rangle \\ &\quad - \mu \langle |u|^{p(\cdot)-2} u, \phi \rangle - \langle Q(\tau, \cdot, u, u_t) - f(\tau, \cdot, u), \phi \rangle \} d\tau \end{aligned}$$

for all $t \in \mathbb{R}_0^+$ and $\phi \in K$;

(B) *Energy Conservation*

- (i) $\mathcal{D}u(t) = \langle Q(t, \cdot, u(t, \cdot), u_t(t, \cdot)), u_t(t, \cdot) \rangle + \mathcal{F}_t u(t) \in L^1_{\text{loc}}(\mathbb{R}_0^+)$,
- (ii) $Eu(t) \leq Eu(0) - \int_0^t \mathcal{D}u(\tau) d\tau$ for all $t \in \mathbb{R}_0^+$.

In general it is important to consider (weak) solutions instead of strong solutions, namely functions $u \in K$ satisfying (A), (B)-(i), while (B)-(ii) is replaced by the *Strong Energy Conservation* (B)_s-(ii), that is $Eu(t) = Eu(0) - \int_0^t \mathcal{D}u(\tau) d\tau$ for all $t \in \mathbb{R}_0^+$. The main reason was first given in [20, Remark 4 at page 199]; see also [21, Remark 2 at page 49] and the discussion in [17, page 345]. Of course if u is a strong solution, then Eu is non-increasing in \mathbb{R}_0^+ and this makes the analysis much simpler. We refer also to the Remark 4.1.

Remark 3.1. If $u \in K$ is a solution of (1.1) in $\mathbb{R}_0^+ \times \Omega$, then by (3.1)₂ there exists always $w_1 \geq 0$ such that $\mathcal{A}u(t) \geq w_1$ for all $t \in \mathbb{R}_0^+$. Hence by (3.1)₁, (B)-(ii) and (\mathcal{F}_2) we get $\mathcal{F}u(t) \geq w_1 - Eu(0) \geq -Eu(0)$ for all $t \in \mathbb{R}_0^+$, in other words $\mathcal{F}u$ is bounded below in \mathbb{R}_0^+ along any solution $u \in K$.

In order to state our main result we consider the following condition:

(\mathcal{F}_3) *There exists a function $q \in C_+(\overline{\Omega})$ satisfying the restriction*

$$\max\{2, \gamma p_+\} < q_-, \tag{3.4}$$

with the property that for all $\mathfrak{F} > 0$ and $\phi \in K$ for which $\inf_{t \in \mathbb{R}_0^+} \mathcal{F}\phi(t) \geq \mathfrak{F}$, there exist $c_1 = c_1(\mathfrak{F}, \phi) > 0$ and $\varepsilon_0 = \varepsilon_0(\mathfrak{F}, \phi) > 0$, such that

(i)

$$\mathcal{F}\phi(t) \leq c_1 \rho_{q(\cdot)}(\phi(t, \cdot)) \text{ for all } t \in \mathbb{R}_0^+,$$

and for all $\varepsilon \in (0, \varepsilon_0)$ there exists $c_2 = c_2(\mathfrak{F}, \phi, \varepsilon) > 0$, such that

(ii)

$$\langle f(t, \cdot, \phi(t, \cdot)), \phi(t, \cdot) \rangle - (q_- - \varepsilon) \mathcal{F}\phi(t) \geq c_2 \rho_{q(\cdot)}(\phi(t, \cdot)) \text{ for all } t \in \mathbb{R}_0^+.$$

In general the function $q \in C_+(\overline{\Omega})$ verifies further restrictions than (3.4) in order to get the validity of (\mathcal{F}_1) and (\mathcal{F}_2), see Section 4 for concrete examples.

Theorem 3.1. *Assume (\mathcal{M}), (\mathcal{F}_1) and (\mathcal{F}_2). If $u \in K$ is a solution of (1.1) in $\mathbb{R}_0^+ \times \Omega$, then $w_2 = \inf_{t \in \mathbb{R}_0^+} \mathcal{F}u(t) > -\infty$. If there exists $\varpi > -1$ such that $Eu(0) < \varpi w_2$, then $w_2 > 0$.*

Finally, if also (\mathcal{F}_3) holds, then there are no solutions $u \in K$ of (1.1) in $\mathbb{R}_0^+ \times \Omega$, for which

$$Eu(0) < \left(\frac{q_-}{\gamma p_+} - 1\right) w_2 = \tilde{E}_1, \tag{3.5}$$

and for which there exist $T \geq 0, q_1 > 0, m > 1, \kappa \geq -m$, with $m + \kappa < q_-$, and non-negative functions $\delta \in L_{loc}^\infty(J), \psi, k \in W_{loc}^{1,1}(J), J = [T, \infty)$, with $k' \geq 0, \psi > 0$ in J and $\psi'(t) = o(\psi(t))$ as $t \rightarrow \infty$, such that

$$(\mathcal{Q}) \quad \langle Q(t, \cdot, u(t, \cdot), u_t(t, \cdot)), u(t, \cdot) \rangle \leq q_1 \delta(t)^{1/m} \mathcal{D}u(t)^{1/m'} \|u(t, \cdot)\|_{q(\cdot)}^{1+\kappa/m}$$

for all $t \in J$, and

$$\delta \leq (k/\psi)^{m-1} \text{ in } J, \quad \int^\infty \psi(t) [\max\{k(t), \psi(t)\}]^{-(1+\theta)} dt = \infty, \tag{3.6}$$

for some appropriate constant $\theta \in (0, \theta_0)$, where

$$\theta_0 = \min \left\{ \frac{q_- - 2}{q_- + 2}, \frac{q_- - m - \kappa}{m(1 + q_+) + \kappa - q_-} \right\}. \tag{3.7}$$

Proof. Let $u \in K$ be a solution of (1.1) in $\mathbb{R}_0^+ \times \Omega$. Clearly $\mathcal{A}u$ and $\mathcal{F}u$ are bounded below in \mathbb{R}_0^+ as shown in Remark 3.1. In particular $w_2 > -\infty$ and $\inf_{t \in \mathbb{R}_0^+} \mathcal{A}u(t) \geq w_1$ for some $w_1 \geq 0$. Assume that $Eu(0) < \varpi w_2$, with $\varpi > -1$. Then $\mathcal{F}u(t) \geq w_1 - Eu(0) > w_1 - \varpi w_2$, which gives $w_2 > w_1/(1 + \varpi) \geq 0$, and so $w_2 > 0$.

Suppose now that also (\mathcal{F}_3) holds and by contradiction that there exists a solution $u \in K$ of (1.1) in $\mathbb{R}_0^+ \times \Omega$, satisfying (\mathcal{Q}) and (3.5)–(3.7) as in the statement. Then $\tilde{E}_1 > 0$ since (3.4) is in charge, so that $\varpi = -1 + q_-/\gamma p_+ > -1$. By the first part of the theorem $w_2 > 0$ and so $\tilde{E}_1 > 0$ by (3.4). Fix $E_2 \geq 0$ in the interval $(Eu(0), \tilde{E}_1)$ and define the function

$$\mathcal{H}(t) = E_2 - Eu(0) + \int_0^t \mathcal{D}u(\tau) d\tau$$

for each $t \in \mathbb{R}_0^+$. Of course \mathcal{H} is well defined and non-decreasing by (B)-(i) and (\mathcal{F}_2) , being $\mathcal{D} \geq 0$ and finite along u . Hence, by (B)-(ii),

$$E_2 - Eu(t) \geq \mathcal{H}(t) \geq \mathcal{H}_0 = E_2 - Eu(0) > 0 \text{ for } t \in \mathbb{R}_0^+, \tag{3.8}$$

where $\mathcal{H}_0 = \mathcal{H}(0)$. Moreover, by (3.8), (3.1), the choice of E_2 and the definition of w_2 , it follows that

$$\begin{aligned} \mathcal{H}(t) &\leq E_2 - Eu(t) < \tilde{E}_1 + \mathcal{F}u(t) \leq \left(\frac{q_-}{\gamma p_+} - 1\right) \mathcal{F}u(t) + \mathcal{F}u(t) \\ &= \frac{q_-}{\gamma p_+} \mathcal{F}u(t) \end{aligned} \tag{3.9}$$

for all $t \in \mathbb{R}_0^+$. In correspondence to $\mathfrak{F} = w_2 > 0$, $\phi = u \in K$, there exists $\varepsilon_0 = \varepsilon_0(w_2, u) > 0$ such that (\mathcal{F}_3) holds true and, without loss of generality, we take $\varepsilon_0 > 0$ so small that

$$\varepsilon_0 w_2 \leq (q_- - \gamma p_+) w_2 - \gamma p_+ E_2, \tag{3.10}$$

which is possible since $w_2 > 0$ and $E_2 < \tilde{E}_1$. Note that (3.10) forces $\varepsilon_0 \leq q_- - \gamma p_+$, being $E_2 \geq 0$.

Fix $\varepsilon \in (0, \varepsilon_0)$ and take $\phi = u$ in the *Distribution Identity* (A). By (3.1)

$$\begin{aligned} \frac{d}{dt} \langle u_t(t, \cdot), u(t, \cdot) \rangle &= c_3 \|u_t(t, \cdot)\|_2^2 + (q_- - \varepsilon) \mathcal{A}u(t) - \langle Au(t, \cdot), u(t, \cdot) \rangle \\ &\quad + \langle f(t, \cdot, u(t, \cdot)), u(t, \cdot) \rangle - (q_- - \varepsilon) \mathcal{F}u(t) \\ &\quad - (q_- - \varepsilon) Eu(t) - \langle Q(t, \cdot, u(t, \cdot), u_t(t, \cdot)), u(t, \cdot) \rangle, \end{aligned}$$

where $c_3 = 1 + (q_- - \varepsilon)/2 > 0$ by the choice of ε . By (3.3), applying (\mathcal{F}_3) -(ii) with $c_2 = c_2(w_2, u, \varepsilon) > 0$, we obtain for all $t \in \mathbb{R}_0^+$

$$\begin{aligned} \frac{d}{dt} \langle u_t(t, \cdot), u(t, \cdot) \rangle &\geq c_3 \|u_t(t, \cdot)\|_2^2 + c_2 \rho_{q(\cdot)}(u(t, \cdot)) - (q_- - \varepsilon) Eu(t) \\ &\quad - \langle Q(t, \cdot, u(t, \cdot), u_t(t, \cdot)), u(t, \cdot) \rangle + (q_- - \varepsilon - \gamma p_+) \mathcal{A}u(t). \end{aligned}$$

Hence by (3.1) and by the definition of w_2 , since $\varepsilon < q_- - \gamma p_+$ by (3.10) and $Eu \leq E_2 - \mathcal{H}$ by (3.8), we have

$$\begin{aligned} \frac{d}{dt} \langle u_t(t, \cdot), u(t, \cdot) \rangle &\geq \tilde{c}_3 \|u_t(t, \cdot)\|_2^2 + c_2 \rho_{q(\cdot)}(u(t, \cdot)) + (q_- - \varepsilon - \gamma p_+) w_2 \\ &\quad - \langle Q(t, \cdot, u(t, \cdot), u_t(t, \cdot)), u(t, \cdot) \rangle - \gamma p_+ Eu(t) \\ &\geq \tilde{c}_3 \|u_t(t, \cdot)\|_2^2 + c_2 \rho_{q(\cdot)}(u(t, \cdot)) + (q_- - \varepsilon - \gamma p_+) w_2 \\ &\quad - \langle Q(t, \cdot, u(t, \cdot), u_t(t, \cdot)), u(t, \cdot) \rangle + \gamma p_+ \mathcal{H}(t) - \gamma p_+ E_2, \end{aligned}$$

where $\tilde{c}_3 = 1 + \gamma p_+/2$. Consequently,

$$\begin{aligned} \frac{d}{dt} \langle u_t(t, \cdot), u(t, \cdot) \rangle &\geq \tilde{c}_3 \|u_t(t, \cdot)\|_2^2 + c_2 \rho_{q(\cdot)}(u(t, \cdot)) + \gamma p_+ \mathcal{H}(t) \\ &\quad - \langle Q(t, \cdot, u(t, \cdot), u_t(t, \cdot)), u(t, \cdot) \rangle, \end{aligned} \tag{3.11}$$

again by (3.10).

By (\mathcal{F}_3) -(i), if $\|u(t, \cdot)\|_{q(\cdot)} \geq 1$ then $\mathcal{F}u(t) \leq c_1 \|u(t, \cdot)\|_{q(\cdot)}^{q_+}$ by (2.1)₁. On the other hand, if $\|u(t, \cdot)\|_{q(\cdot)} \leq 1$ then $w_2 \leq c_1 \|u(t, \cdot)\|_{q(\cdot)}^{q_-}$ by (\mathcal{F}_3) -(i), the definition of w_2 and (2.1)₂. Hence $\|u(t, \cdot)\|_{q(\cdot)} \geq (w_2/c_1)^{1/q_-} > 0$, so that $\mathcal{F}u(t) \leq c_1 \rho_{q(\cdot)}(u(t, \cdot)) \leq c_1 (c_1/w_2)^{q_+/q_-} \|u(t, \cdot)\|_{q(\cdot)}^{q_+}$ by (\mathcal{F}_3) -(i). In conclusion, along the solution u , we have for all $t \in \mathbb{R}_0^+$

$$\mathcal{F}u(t) \leq \tilde{c}_1 \|u(t, \cdot)\|_{q(\cdot)}^{q_+}, \text{ with } \tilde{c}_1 = \max\{c_1, c_1(c_1/w_2)^{q_+/q_-}\}.$$

Hence, by (Q) and (3.9)

$$\begin{aligned} & \langle Q(t, \cdot, u(t, \cdot), u_t(t, \cdot)), u(t, \cdot) \rangle \\ & \leq q_1 \|u(t, \cdot)\|_{q(\cdot)}^{q_-/m} \left(\delta(t)^{1/(m-1)} \mathcal{D}u(t) \right)^{1/m'} \|u(t, \cdot)\|_{q(\cdot)}^{-q_+ \bar{r}} \\ & \leq \tilde{c}_1^{\bar{r}} q_1 \|u(t, \cdot)\|_{q(\cdot)}^{q_-/m} \left(\delta(t)^{1/(m-1)} \mathcal{D}u(t) \right)^{1/m'} [\mathcal{F}u(t)]^{-\bar{r}} \\ & \leq c_4 \|u(t, \cdot)\|_{q(\cdot)}^{q_-/m} \left(\delta(t)^{1/(m-1)} \mathcal{D}u(t) \right)^{1/m'} [\mathcal{H}(t)]^{-\bar{r}} \end{aligned}$$

for all $t \in J$, where $c_4 = (\tilde{c}_1 q_- / \gamma p_+)^{\bar{r}} q_1$ and

$$\bar{r} = \frac{q_- - m - \kappa}{mq_+} \in (0, 1), \tag{3.12}$$

since $m + \kappa < q_-$ and $\kappa \geq -m$ by (Q). Put

$$r_0 = \min \left\{ \bar{r}, \frac{1}{2} - \frac{1}{q_-} \right\}. \tag{3.13}$$

Note that θ_0 in (3.7) can be expressed as $\theta_0 = r_0 / (1 - r_0)$, and take from now on $r = \theta / (1 + \theta)$, so that $r \in (0, r_0)$. Consequently, by Young’s inequality, we get

$$\begin{aligned} & \langle Q(t, \cdot, u(t, \cdot), u_t(t, \cdot)), u(t, \cdot) \rangle \\ & \leq \left\{ (c_4 \ell)^m \|u(t, \cdot)\|_{q(\cdot)}^{q_-} + \ell^{-m'} \delta(t)^{1/(m-1)} \mathcal{D}u(t) \right\} [\mathcal{H}(t)]^{-\bar{r}} \\ & \leq (c_4 \ell)^m \mathcal{H}_0^{-\bar{r}} \|u(t, \cdot)\|_{q(\cdot)}^{q_-} + \ell^{-m'} \mathcal{H}_0^{r-\bar{r}} \delta(t)^{1/(m-1)} [\mathcal{H}(t)]^{-r} \mathcal{D}u(t), \end{aligned} \tag{3.14}$$

where in the last step we have used the facts that $\mathcal{H} \geq \mathcal{H}_0$ by (3.8) and that $0 < r < r_0 \leq \bar{r}$ by (3.13). The parameter $\ell > 0$ will be fixed later. Since $\mathcal{D}u = \mathcal{H}'$, we see that $(1 - r)\mathcal{H}^{-r} \mathcal{H}' = [\mathcal{H}^{1-r}]'$. Hence it is convenient to introduce the function

$$\mathcal{Z} = \mathcal{Z}(t) = \lambda k(t) [\mathcal{H}(t)]^{1-r} + \psi(t) \langle u_t, u \rangle,$$

where $\lambda > 0$ is a constant to be fixed later. Clearly $\mathcal{Z} \in W_{\text{loc}}^{1,1}(J)$ by Corollary VIII.9 of [4] and so, almost everywhere in J ,

$$\mathcal{Z}' = \lambda k(1 - r)\mathcal{H}^{-r} \mathcal{H}' + \lambda k' \mathcal{H}^{1-r} + \psi \frac{d}{dt} \langle u_t, u \rangle + \psi' \langle u_t, u \rangle.$$

If $t \in \mathbb{R}_0^+$ and $\rho_{q(\cdot)}(u(t, \cdot)) \geq 1$, then $\rho_{q(\cdot)}(u(t, \cdot)) \geq \|u(t, \cdot)\|_{q(\cdot)}^{q_-}$, by (2.1)₁. Otherwise $\rho_{q(\cdot)}(u(t, \cdot)) \leq 1$, so that by (F₃)-(i) we have $w_2 \leq c_1$ and $\rho_{q(\cdot)}(u(t, \cdot)) \geq w_2 \|u(t, \cdot)\|_{q(\cdot)}^{q_-} / c_1$. Hence for all $t \in \mathbb{R}_0^+$ we get $\rho_{q(\cdot)}(u(t, \cdot)) \geq \min\{1, w_2/c_1\} \|u(t, \cdot)\|_{q(\cdot)}^{q_-}$. Therefore, by (3.11) and (3.14), almost everywhere in J

$$\begin{aligned} \mathcal{Z}' & \geq \lambda k(1 - r)\mathcal{H}^{-r} \mathcal{H}' + \lambda k' \mathcal{H}^{1-r} + \psi' \langle u_t, u \rangle \\ & \quad + \psi \left\{ \tilde{c}_3 \|u_t\|_2^2 + c_2 \rho_{q(\cdot)}(u) + \gamma p_+ \mathcal{H} - \langle Q(t, \cdot, u, u_t), u \rangle \right\} \\ & \geq \left(\lambda k(1 - r) - \ell^{-m'} \mathcal{H}_0^{r-\bar{r}} \delta^{1/(m-1)} \psi \right) \mathcal{H}^{-r} \mathcal{H}' + \gamma p_+ \psi \mathcal{H} + \lambda k' \mathcal{H}^{1-r} \\ & \quad + \psi' \langle u_t, u \rangle + \psi \left\{ \tilde{c}_3 \|u_t\|_2^2 + \tilde{c}_2 \|u\|_{q(\cdot)}^{q_-} - (c_4 \ell)^m \mathcal{H}_0^{-\bar{r}} \|u\|_{q(\cdot)}^{q_-} \right\}, \end{aligned}$$

where $\tilde{c}_2 = \min\{c_2, c_2 w_2/c_1\}$. Thus, almost everywhere in J , by (3.6)₁ and the fact that $\lambda k' \mathcal{H}^{1-r} \geq 0$, we find

$$\begin{aligned} \mathcal{L}' \geq & k \left(\lambda(1-r) - \ell^{-m'} \mathcal{H}_0^{r-\bar{r}} \right) \mathcal{H}^{-r} \mathcal{H}' + \gamma p_+ \psi \mathcal{H} \\ & + \psi' \langle u_t, u \rangle + \psi \left\{ \tilde{c}_3 \|u_t\|_2^2 + \tilde{c}_2 \|u\|_{q(\cdot)}^{q_-} - (c_4 \ell)^m \mathcal{H}_0^{-\bar{r}} \|u\|_{q(\cdot)}^{q_-} \right\}. \end{aligned}$$

Next, from Cauchy's and Young's inequalities, and the definition of K , we have

$$|\langle u_t(t, \cdot), u(t, \cdot) \rangle| \leq \|u_t(t, \cdot)\|_2 \|u(t, \cdot)\|_2 \leq \|u_t(t, \cdot)\|_2^2 + \|u(t, \cdot)\|_2^2. \tag{3.15}$$

Consider now the relation $z^\xi \leq (z+1) \leq (1+1/\eta)(z+\eta)$, which holds for all $z \geq 0$, $\xi \in [0, 1]$, $\eta > 0$, and take $z = \|u(t, \cdot)\|_2^{q_-}$, $\xi = 2/q_- < 1$, since $q_- > 2$ by (3.4), and $\eta = \mathcal{H}_0$, we obtain

$$\|u(t, \cdot)\|_2^2 \leq (1 + 1/\mathcal{H}_0)(\|u(t, \cdot)\|_2^{q_-} + \mathcal{H}_0).$$

Of course the embedding $L^{q(\cdot)}(\Omega) \hookrightarrow L^2(\Omega)$ is continuous by (3.4), and so there exists a positive constant B , independent of u , such that $\|u(t, \cdot)\|_2 \leq B \|u(t, \cdot)\|_{q(\cdot)}$. Combining the last two inequalities, we get

$$\|u(t, \cdot)\|_2^2 \leq c_5 \{ \|u(t, \cdot)\|_{q(\cdot)}^{q_-} + \mathcal{H}(t) \}, \tag{3.16}$$

where $c_5 = (1 + 1/\mathcal{H}_0) \max\{1, B^{q_-}\} > 0$, being $\mathcal{H} \geq \mathcal{H}_0$ in J by (3.8). Then, using (3.15) and (3.16) in the preceding estimate of \mathcal{L}' , we find that

$$\begin{aligned} \mathcal{L}' \geq & k \left\{ \lambda(1-r) - \ell^{-m'} \mathcal{H}_0^{r-\bar{r}} \right\} \mathcal{H}^{-r} \mathcal{H}' \\ & + \psi (\tilde{c}_3 - |\psi'/\psi|) \|u_t\|_2^2 + \psi \{ \gamma p_+ - c_5 |\psi'/\psi| \} \mathcal{H} \\ & + \psi \left\{ \tilde{c}_2 - c_5 |\psi'/\psi| - (c_4 \ell)^m \mathcal{H}_0^{-\bar{r}} \right\} \|u(t, \cdot)\|_{q(\cdot)}^{q_-}. \end{aligned} \tag{3.17}$$

There is $T_1 \in J$ such that $2|\psi'/\psi| \leq \min\{\tilde{c}_3, \gamma p_+/c_5, \tilde{c}_2/c_5\}$ for all $t \in J_1 = [T_1, \infty)$, since $\psi' = o(\psi)$ as $t \rightarrow \infty$. Then we take $\ell > 0$ so small that $4(c_4 \ell)^m \leq \tilde{c}_2 \mathcal{H}_0^{-\bar{r}}$ and $\lambda > 0$ so large that $\lambda \geq \max\{\mathcal{H}_0^{r-\bar{r}}/\ell^{m'}(1-r), 1\}$ and $\mathcal{L}(T_1) > 0$. In conclusion, we have shown that for almost all $t \in J_1$

$$\mathcal{L}'(t) \geq C \psi(t) \left\{ \mathcal{H}(t) + \|u_t(t, \cdot)\|_2^2 + \|u(t, \cdot)\|_{q(\cdot)}^{q_-} \right\}, \tag{3.18}$$

where $2C = \min\{\tilde{c}_2/2, \tilde{c}_3, \gamma p_+\}$. Since $k(T_1), \mathcal{H}(T_1) > 0$, in particular $\mathcal{L}(t) \geq \mathcal{L}(T_1) > 0$ for all $t \in J_1$.

On the other hand, from the definition of \mathcal{L} , we obtain

$$\mathcal{L}^\alpha \leq \left(\lambda k \mathcal{H}^{1/\alpha} + \psi |\langle u_t, u \rangle| \right)^\alpha \leq 2^{\alpha-1} \{ (\lambda k)^\alpha \mathcal{H} + \psi^\alpha \|u_t\|_2^\alpha \|u\|_2^\alpha \}, \tag{3.19}$$

where $\alpha = 1/(1-r)$. Of course, $\alpha \in (1, 2)$ by (3.13) and the choice of r . Put $v = 2/\alpha$, so that $v > 1$. Furthermore,

$$\frac{1}{\alpha v'} = \frac{v-1}{\alpha v} = \frac{1}{\alpha} - \frac{1}{2} = \frac{1}{2} - r > \frac{1}{q_-}$$

by (3.13), and so $\alpha v' < q_-$. Thus, using the relation $z^\xi \leq (z+1) \leq (1+1/\eta)(\eta+z)$ once more, with $z = \|u(t, \cdot)\|_2^{q_-}$, $\xi = \alpha v'/q_- < 1$ and $\eta = \mathcal{H}_0$, it follows that

$$\|u(t, \cdot)\|_2^{\alpha v'} \leq (1+1/\mathcal{H}_0)(\mathcal{H}_0 + \|u(t, \cdot)\|_2^{q_-}) \leq c_5(\mathcal{H}(t) + \|u(t, \cdot)\|_{q(\cdot)}^{q_-}), \quad (3.20)$$

by (3.8), where c_5 is the same constant as in (3.16). Hence, from (3.19), Young's inequality and (3.20), for all $t \in J_1$

$$\begin{aligned} \mathcal{L}(t)^\alpha &\leq 2^{\alpha-1} [\max\{\lambda k(t), \psi(t)\}]^\alpha \left\{ \mathcal{H}(t) + \|u_t(t, \cdot)\|_2^{\alpha v} + \|u(t, \cdot)\|_2^{\alpha v'} \right\} \\ &\leq D [\max\{\lambda k(t), \psi(t)\}]^\alpha \left\{ \mathcal{H}(t) + \|u_t(t, \cdot)\|_2^2 + \|u(t, \cdot)\|_{q(\cdot)}^{q_-} \right\}, \end{aligned}$$

where $D = 2^{\alpha-1}(c_5 + 1)$. Combining this with (3.18) and $\lambda \geq 1$, we obtain almost everywhere in J_1

$$\mathcal{L}^{-\alpha} \mathcal{L}' \geq \frac{C}{D} \psi [\max\{\lambda k, \psi\}]^{-\alpha} \geq c_6 \psi [\max\{k, \psi\}]^{-\alpha},$$

where $c_6 = C/D\lambda^\alpha$. Finally, since $\alpha = 1 + \theta$, being $r = \theta/(1 + \theta)$, by (3.6)₂ we see that \mathcal{L} cannot be global. This completes the proof. \square

Remark 3.2. In [17 and 23–25], assumptions (\mathcal{F}_1) – (\mathcal{F}_3) and (\mathcal{Q}) are required in a stronger form and the main structure geometry there implies in particular

$$\inf_{t \in \mathbb{R}_0^+} \mathcal{A}u(t) \geq w_1 \geq 0, \quad Eu(0) < E_1 = \left(1 - \frac{\gamma p_+}{q_-}\right) w_1. \quad (3.21)$$

Observe that condition (3.21)₁ is always true and so $\mathcal{F}u(t) \geq w_1 - Eu(0)$ as noted in Remark 3.1. Hence $w_2 > w_1 - E_1 = \gamma p_+ w_1/q_-$ when (3.21) holds. This yields $\tilde{E}_1 > E_1 \geq 0$. Therefore (3.5) is always weaker than (3.21). Of course in (3.21) the case $w_1 > 0$ is more interesting, see [23], while the case $w_1 = 0$ was early treated in [17].

From the first part of Theorem 3.1 under (\mathcal{F}_1) – (\mathcal{F}_2) it is evident that if $u \in K$ is a solution of (1.1) in $\mathbb{R}_0^+ \times \Omega$ and $w_2 = \inf_{t \in \mathbb{R}_0^+} \mathcal{F}u(t) \leq 0$ then $Eu(0) \geq \tilde{E}_1$. Hence, being $w_1 \leq Eu(0) + w_2 \leq Eu(0)$ by (3.1), also the case (3.21) can never occur, since $E_1 < w_1$.

4. Applications of the main theorem

In this section we present useful consequences of Theorem 3.1 and a qualitative analysis, interesting in several applications. Suppose that M and f verify

$$M(\tau) = a + b\gamma\tau^{\gamma-1}, \quad a, b \geq 0, \quad a + b > 0, \quad \gamma \begin{cases} > 1, & \text{if } b > 0, \\ = 1, & \text{if } b = 0, \end{cases} \quad (4.1)$$

$$f(t, x, u) = g(t, x)|u|^{\sigma(x)-2}u + c(x)|u|^{q(x)-2}u,$$

where $\sigma, q \in C_+(\overline{\Omega})$, $c \in L^\infty(\Omega)$ is a non-negative function, $g \in C(\mathbb{R}_0^+ \times \Omega)$ is differentiable with respect to t and $g_t \in C(\mathbb{R}_0^+ \times \Omega)$; moreover

$$\begin{aligned} &\sigma_+ \leq q_-, \max\{2, \gamma p_+\} < q_- \leq q \leq p^* \text{ in } \Omega, \text{ and } c = \|c\|_\infty > 0; \\ &0 \leq -g(t, x), g_t(t, x) \leq h(x) \text{ in } \mathbb{R}_0^+ \times \Omega, \text{ for some } h \in L^1(\Omega), \\ &g(t, \cdot) \in L^{\wp(\cdot)}(\Omega) \text{ in } \mathbb{R}_0^+, \text{ where} \tag{4.2} \\ &\wp(x) = \begin{cases} q(x)/[q(x) - \sigma(x)], & \text{if } \sigma_+ < q_-, \\ \infty, & \text{if } \sigma_+ = q_-. \end{cases} \end{aligned}$$

Lemma 4.1. Assume that M and f verify (4.1) and (4.2). Then (\mathcal{M}) , (\mathcal{F}_1) , (\mathcal{F}_2) and (\mathcal{F}_3) -*(i)* hold. Furthermore, if in addition

$$\sigma_+ < q_- \text{ and } \bar{c} = \text{ess inf}_{\overline{\Omega}} c(x) > 0, \tag{4.3}$$

then (\mathcal{F}_3) -*(ii)* is verified, and in particular

$$\langle f(t, \cdot, \phi(t, \cdot)), \phi(t, \cdot) \rangle \geq q_- \mathcal{F} \phi(t) \text{ for all } \phi \in K \text{ and } t \in \mathbb{R}_0^+. \tag{4.4}$$

Proof. Of course (\mathcal{M}) is satisfied. For any $\phi \in K$,

$$|\langle f(t, x, \phi(t, x)), \phi(t, x) \rangle| \leq -g(t, x)|\phi(t, x)|^{\sigma(x)} + c|\phi(t, x)|^{q(x)},$$

so that by (4.2) we have $(f(t, x, \phi(t, x)), \phi(t, x)) \in L^1(\Omega)$ for all $t \in \mathbb{R}_0^+$ and $\langle f(t, \cdot, \phi(t, \cdot)), \phi(t, \cdot) \rangle \in L^1_{\text{loc}}(\mathbb{R}_0^+)$. Analogously, being

$$F(t, x, \phi(t, x)) = g(t, x) \frac{|\phi(t, x)|^{\sigma(x)}}{\sigma(x)} + c(x) \frac{|\phi(t, x)|^{q(x)}}{q(x)},$$

then also $F(t, x, \phi(t, x)) \in L^1(\Omega)$ for all $t \in \mathbb{R}_0^+$. Hence (\mathcal{F}_1) holds. Furthermore, for any $\phi \in K$

$$\mathcal{F} \phi(t) = \mathcal{F}(t, \phi) = \int_{\Omega} \left\{ g(t, x) \frac{|\phi(t, x)|^{\sigma(x)}}{\sigma(x)} + c(x) \frac{|\phi(t, x)|^{q(x)}}{q(x)} \right\} dx. \tag{4.5}$$

The same expression holds for $\mathcal{F}(t, w)$ when $(t, w) \in \mathbb{R}_0^+ \times W_0^{1,p(\cdot)}(\Omega)$. Thus, differentiation under the integral sign gives

$$\mathcal{F}_t(t, w) = \int_{\Omega} g_t(t, x) \frac{|w(x)|^{\sigma(x)}}{\sigma(x)} dx.$$

Hence $\mathcal{F}_t \geq 0$ in $\mathbb{R}_0^+ \times W_0^{1,p(\cdot)}(\Omega)$ by (4.2), and so (\mathcal{F}_2) is fulfilled.

By (4.5) for all $\phi \in K$

$$\mathcal{F} \phi(t) \leq \int_{\Omega} c(x) \frac{|\phi(t, x)|^{q(x)}}{q(x)} dx \leq \frac{c}{q_-} \rho_{q(\cdot)}(\phi(t, \cdot)), \tag{4.6}$$

being $g \leq 0$. Hence, (\mathcal{F}_3) -*(i)* holds for all $\mathfrak{F} \geq 0$, taking $c_1 = c/q_-$.

Assume now also (4.3) and put $\varepsilon_0 = q_- - \sigma_+ > 0$, so that for all $\varepsilon \in (0, \varepsilon_0)$ and $\phi \in K$, by (4.1)–(4.5), we have

$$\begin{aligned} & \langle f(t, \cdot, \phi(t, \cdot)), \phi(t, \cdot) \rangle - (q_- - \varepsilon) \mathcal{F} \phi(t) \\ & \geq \left(1 - \frac{q_- - \varepsilon}{\sigma_+} \right) \int_{\Omega} g(t, x) |\phi(t, x)|^{\sigma(x)} dx + \frac{\varepsilon}{q_-} \int_{\Omega} c(x) |\phi(t, x)|^{q(x)} dx \\ & \geq \frac{\bar{c}\varepsilon}{q_-} \rho_{q(\cdot)}(\phi(t, \cdot)). \end{aligned}$$

Thus, (\mathcal{F}_3) -(ii) is fulfilled, with $c_2 = \bar{c}\varepsilon/q_- > 0$ and \bar{c} given in (4.3). Letting $\varepsilon \rightarrow 0$ in the above inequality, we get at once (4.4). \square

In [23–25] assumptions (4.1)–(4.3) trivially hold, with $g \equiv 0$, $c \equiv 1$, $p \equiv 2$ and also q, γ constant with $q > 2\gamma$, and of course $\gamma = 1$ in [23, 24].

Lemma 4.2. *Assume that the continuous damping function Q given in the Introduction verifies also the pointwise condition (Q_1) There exist constants $t_Q \geq 0$, $m > 1$ and $\kappa \geq 0$, with $m + \kappa < q_-$, and a non-negative function $d \in C(\mathbb{R}_0^+ \rightarrow L^{q_-/(q_- - \kappa - m)}(\Omega))$ such that*

$$|Q(t, x, u, v)| \leq [d(t, x)|u|^\kappa]^{1/m} (Q(t, x, u, v), v)^{1/m'} \tag{4.7}$$

whenever $(t, x, u, v) \in [t_Q, \infty) \times \Omega \times \mathbb{R}^N \times \mathbb{R}^N$. Then (Q) is satisfied along any solution u of the problem (1.1), with $T \geq t_Q$ and $\delta(t) = \|d(t, \cdot)\|_{q_-/(q_- - \kappa - m)} \in C(\mathbb{R}_0^+)$, provided that (\mathcal{F}_2) holds.

Proof. Clearly $\langle Q(t, \cdot, u(t, \cdot), u_t(t, \cdot)), u_t(t, \cdot) \rangle \geq 0$ for each $t \geq 0$ along any solution $u \in K$ of the problem (1.1), and so $\mathcal{D}u \geq 0$, since also $\mathcal{F}_t u \geq 0$ in \mathbb{R}_0^+ by (\mathcal{F}_2) , and $\mathcal{D}u$ is finite in \mathbb{R}_0^+ along u by (B)-(i).

By (4.7) and Hölder’s inequality, for each $t \geq t_Q$, along any solution u of (1.1),

$$\begin{aligned} & \|Q(t, \cdot, u(t, \cdot), u_t(t, \cdot))\|_{q'_-} \\ & \leq \left(\int_{\Omega} \{d(t, x)|u(t, x)|^\kappa\}^{\frac{q_-}{q_- - m}} dx \right)^{\frac{q_- - m}{mq_-}} \langle Q(t, \cdot, u, u_t), u_t(t, \cdot) \rangle^{1/m'}, \end{aligned}$$

where $q'_- = (q_-)' = q_+/(q_+ - 1)$. On the other hand, applying once again Hölder’s inequality, we find that

$$\int_{\Omega} \{d(t, x)|u(t, x)|^\kappa\}^{\frac{q_-}{q_- - m}} dx \leq \left(\int_{\Omega} d^{\frac{q_-}{q_- - m - \kappa}} dx \right)^{\frac{q_- - m - \kappa}{q_- - m}} \left(\int_{\Omega} |u|^{q_-} dx \right)^{\frac{\kappa}{q_- - m}}.$$

Hence, combining the last two inequalities, we get by (\mathcal{F}_2)

$$\begin{aligned} \|Q(t, \cdot, u(t, \cdot), u_t(t, \cdot))\|_{q'_-} & \leq \|d(t, \cdot)\|_{\frac{q_-}{q_- - \kappa - m}}^{\frac{1}{m}} \|u(t, \cdot)\|_{q_-}^{\frac{\kappa}{m}} \langle Q(t, \cdot, u, u_t), u_t(t, \cdot) \rangle^{\frac{1}{m'}} \\ & \leq \delta(t)^{1/m} \|u(t, \cdot)\|_{q_-}^{\kappa/m} \mathcal{D}u(t)^{1/m'}, \end{aligned}$$

where $\delta(t) = \|d(t, \cdot)\|_{q_-(q_-\kappa-m)} \in C(\mathbb{R}_0^+)$ by (Q_1) , so that $\delta \in L_{\text{loc}}^\infty(\mathbb{R}_0^+)$, while $q'_- = q_+/(q_+ - 1)$, as above. By the obvious continuity of the embedding $L^{q(\cdot)}(\Omega) \hookrightarrow L^{q_-}(\Omega)$ there is a constant $B_1 > 0$ independent of u such that $\|u(t, \cdot)\|_{q_-} \leq B_1 \|u(t, \cdot)\|_{q(\cdot)}$ for all $t \in \mathbb{R}_0^+$. Hence

$$\begin{aligned} | \langle Q(t, \cdot, u, u_t), u(t, \cdot) \rangle | &\leq \|Q(t, \cdot, u, u_t)\|_{q'_-} \|u(t, \cdot)\|_{q_-} \\ &\leq q_1 \delta(t)^{1/m} \|u(t, \cdot)\|_{q(\cdot)}^{1+\kappa/m} \mathcal{D}u(t)^{1/m'}, \end{aligned} \tag{4.8}$$

where $q_1 = B_1^{1+\kappa/m}$. \square

Of course in [23–25] assumption (Q_1) is automatic, with $\kappa \equiv 0$ and $1 < m < q$, being there $q_- = q_+ = q$.

Let us now distinguish two cases, depending on whether b is zero or not. Of course, when $b > 0$ and $a = 0$ we are in the so called *degenerate case*, which is in our context more interesting. Recall that we have assumed $\gamma > 1$ when $b > 0$, while $\gamma = 1$ if $b = 0$, and put $s = b$ if $b > 0$, while $s = a$ if $b = 0$.

Lemma 4.3. *Assume (4.1) and (4.2). If $u \in K$ is a solution of (1.1) in $\mathbb{R}_0^+ \times \Omega$, then for all $t \in \mathbb{R}_0^+$*

$$Eu(t) \geq \frac{s}{(\Lambda p_+)^{\gamma}} \min \{v(t)^{p_-}, v(t)^{p_+}\}^{\gamma} - \frac{c}{q_-} \max\{v(t)^{q_-}, v(t)^{q_+}\},$$

where $v(t) = \|u(t, \cdot)\|_{q(\cdot)}$,

$$\Lambda = \max \left\{ \lambda_{q(\cdot)}^{p_+}, \lambda_{q(\cdot)}^{p_-}, (s\gamma/c p_+^{\gamma-1})^{1/\gamma} \right\} \tag{4.9}$$

and $\lambda_{q(\cdot)}$ is the constant introduced in (2.3).

Proof. Let $u \in K$ be a solution of (1.1) in $\mathbb{R}_0^+ \times \Omega$. By (2.1) and (2.3) we have

$$\begin{aligned} \mathcal{A}u(t) &\geq \mathcal{M}(\mathcal{I}u(t)) \geq \frac{a}{p_+} \rho_{p(\cdot)}(Du(t, \cdot)) + \frac{b}{p_+^{\gamma}} [\rho_{p(\cdot)}(Du(t, \cdot))]^{\gamma} \\ &\geq \frac{a}{p_+} \min \left\{ \|Du(t, \cdot)\|_{p(\cdot)}^{p_-}, \|Du(t, \cdot)\|_{p(\cdot)}^{p_+} \right\} \\ &\quad + \frac{b}{p_+^{\gamma}} \min \left\{ \|Du(t, \cdot)\|_{p(\cdot)}^{\gamma p_-}, \|Du(t, \cdot)\|_{p(\cdot)}^{\gamma p_+} \right\} \\ &\geq \frac{a}{\Lambda p_+} \min \left\{ \|u(t, \cdot)\|_{q(\cdot)}^{p_-}, \|u(t, \cdot)\|_{q(\cdot)}^{p_+} \right\} \\ &\quad + \frac{b}{(\Lambda p_+)^{\gamma}} \min \left\{ \|u(t, \cdot)\|_{q(\cdot)}^{\gamma p_-}, \|u(t, \cdot)\|_{q(\cdot)}^{\gamma p_+} \right\} \\ &\geq \frac{s}{(\Lambda p_+)^{\gamma}} \min \{v(t)^{p_-}, v(t)^{p_+}\}^{\gamma}. \end{aligned} \tag{4.10}$$

Therefore, since $Eu(t) \geq \mathcal{A}u(t) - \mathcal{F}u(t)$ for each $t \in \mathbb{R}_0^+$ by (3.1), the assertion follows at once by (4.10) and (4.6). \square

From Lemma 4.3 we obtain

$$Eu(t) \geq \varphi(v(t)) \quad \text{for all } t \in \mathbb{R}_0^+, \tag{4.11}$$

where $\varphi : \mathbb{R}_0^+ \rightarrow \mathbb{R}$ is defined by $\varphi(v) = \varphi_1(v)$ if $v \in [0, 1]$, while $\varphi(v) = \varphi_2(v)$ if $v \geq 1$, with

$$\varphi_1(v) = \frac{s}{(\Lambda p_+)^{\gamma}} v^{\gamma p_+} - \frac{c}{q_-} v^{q_-}, \quad \varphi_2(v) = \frac{s}{(\Lambda p_+)^{\gamma}} v^{\gamma p_-} - \frac{c}{q_-} v^{q_+}.$$

It is easy to see that φ attains its maximum at

$$v_1 = a_1^{1/(q_- - \gamma p_+)}, \quad \text{where } a_1 = \frac{s \gamma p_+}{c (\Lambda p_+)^{\gamma}}. \tag{4.12}$$

The choice of Λ in (4.9) guarantees that $v_1 \in (0, 1]$. Clearly φ_2 takes its maximum at $v_2 = a_2^{1/(q_+ - \gamma p_-)}$, where $a_2 = p_- q_- a_1 / p_+ q_+ \leq a_1 \leq 1$. Hence φ is strictly decreasing for $v \geq v_1$, with $\varphi(v) \rightarrow -\infty$ as $v \rightarrow \infty$. Finally,

$$\varphi(v_1) = \left(1 - \frac{\gamma p_+}{q_-}\right) w_1 = E_1 > 0, \quad \text{where } w_1 = \frac{s v_1^{\gamma p_+}}{(\Lambda p_+)^{\gamma}} > 0. \tag{4.13}$$

Put

$$\Sigma = \{(v, E) \in \mathbb{R}^2 : v > v_1, E < E_1\}.$$

Theorem 4.1. *Assume (4.1), (4.2) and (Q₁). If $u \in K$ is a solution of (1.1) in $\mathbb{R}_0^+ \times \Omega$, then $w_2 = \inf_{t \in \mathbb{R}_0^+} \mathcal{F}u(t) > -\infty$. If, furthermore, $Eu(0) < \tilde{E}_1$, with \tilde{E}_1 given in (3.5), then $w_2 > 0$ and $(v(t), Eu(t)) \in \tilde{\Sigma}$ for all $t \in \mathbb{R}_0^+$, where*

$$\tilde{\Sigma} = \{(v, E) \in \mathbb{R}^2 : v > v_1, E < \tilde{E}_1\}, \tag{4.14}$$

and v_1 is defined in (4.12). Consequently, if in addition (4.3) holds, then there are no solutions $u \in K$ of the problem (1.1) in $\mathbb{R}_0^+ \times \Omega$, with $Eu(0) < \tilde{E}_1$, for which there exist positive functions ψ, k verifying (3.6)–(3.7) as in Theorem 3.1.

Proof. Clearly Lemmas 4.1 and 4.2 are available, so that assumptions (\mathcal{F}_1), (\mathcal{F}_2), (\mathcal{F}_3)-(i) and (Q) of Theorem 3.1 are satisfied along any solution u of (1.1). The fact that w_2 is finite and positive are an immediate consequence of Theorem 3.1. By (\mathcal{F}_2), (Q₁) and (B)-(ii) clearly $Eu(t) \leq Eu(0) < \tilde{E}_1$ for all $t \in \mathbb{R}_0^+$.

Suppose now that there exists $t_1 \in \mathbb{R}_0^+$ such that $v(t_1) \leq v_1$. Then, by (4.6) and (2.1)₂ we have $w_2 \leq \mathcal{F}u(t_1) \leq cv(t_1)^{q_-}/q_-$. On the other hand, $\mathcal{A}u(t_1) \geq sv(t_1)^{\gamma p_+}/(\Lambda p_+)^{\gamma}$ by (4.10). Now, by (3.1), (\mathcal{F}_2), (Q₁) and (B)-(ii), it follows that

$$\begin{aligned} \left(\frac{q_-}{\gamma p_+} - 1\right) \frac{c}{q_-} v(t_1)^{q_-} &\geq \tilde{E}_1 > Eu(0) \geq \mathcal{A}u(t_1) - \mathcal{F}u(t_1) \\ &\geq \frac{s}{(\Lambda p_+)^{\gamma}} v(t_1)^{\gamma p_+} - \frac{c}{q_-} v(t_1)^{q_-}. \end{aligned}$$

That is $v(t_1) > [s \gamma p_+ / c (\Lambda p_+)^{\gamma}]^{1/(q_- - \gamma p_+)} = v_1$ by (4.12). This is an obvious contradiction. Therefore $v(t) > v_1$ for all $t \in \mathbb{R}_0^+$, and $(v(t), Eu(t)) \in \tilde{\Sigma}$ for all $t \in \mathbb{R}_0^+$, as required.

The last part of the theorem is again a direct consequence of Theorem 3.1. \square

If $\mu = 0$, f is as in (4.1)–(4.3), with $g(t, x) = g(x)$, and $Q(t, x, u, 0) = 0$ in (Q_1) , then any stationary solution $u = u(x)$ of (1.1), with $w_2 = \mathcal{F}u > 0$, has the property that $Eu \geq \tilde{E}_1$, that is Theorem 4.1 can never be applied. Indeed, in this case $Eu, \mathcal{A}u$ and $\mathcal{F}u > 0$ are constant in t . Hence by (3.1), (3.3) and (4.4), since $\langle Au, u \rangle = \langle f(\cdot, u), u \rangle$ being u a stationary solution of (1.1),

$$Eu = \left(\frac{\mathcal{A}u}{\mathcal{F}u} - 1 \right) \mathcal{F}u \geq \left(\frac{q_-}{\gamma p_+} - 1 \right) \mathcal{F}u = \left(\frac{q_-}{\gamma p_+} - 1 \right) w_2 = \tilde{E}_1,$$

as claimed.

In special reverse situations in which the external force f is of restoring type, it is possible to show that if $v(0) < v_1$ and $Eu(0) < E_1$, then $v(t) < v_1$ and $Eu(t) < E_1$ for all $t \in \mathbb{R}_0^+$, that is any point $(v(t), Eu(t))$ on the trajectory of a global strong solution $u \in K$ must remain in the potential well, see, for example, [3, Lemma 4.3] and for dissipative wave systems [21, Remark on page 45], as well as the references therein.

The global nonexistence results, given in [17] and [23–25] in special subcases of this paper, concern only the region Σ which is smaller than $\tilde{\Sigma}$. Indeed, if $Eu(0) < \tilde{E}_1$, under the assumptions of Theorem 4.1, then for all $t \geq 0$

$$v(t) > v_1, \quad \mathcal{A}u(t) > \frac{s}{(\Lambda p_+)^{\gamma}} \min \{v_1^{p_-}, v_1^{p_+}\}^{\gamma} = w_1 > 0, \quad (4.15)$$

by (4.10) and (4.13). Hence, $E_1 < \tilde{E}_1$ as already proved in Remark 3.2. In any case we present also new results under the assumption $Eu(0) \leq E_1$, the first of which being the following

Theorem 4.2. Assume (4.1), (4.2) and (Q_1) . Let $u \in K$ be a solution of (1.1) in $\mathbb{R}_0^+ \times \Omega$, such that $Eu(0) < E_1$, with E_1 given in (4.13). Then $v_1 \notin \overline{v(\mathbb{R}_0^+)}$ and $w_2 = \inf_{t \in \mathbb{R}_0^+} \mathcal{F}u(t) \neq \gamma p_+ w_1 / q_-$, where v_1 and w_1 are defined in (4.12) and (4.13), respectively. Moreover, $w_2 > \gamma p_+ w_1 / q_-$ if and only if $\overline{v(\mathbb{R}_0^+)} \subset (v_1, \infty)$.

Proof. Let $u \in K$ be a solution of (1.1) in $\mathbb{R}_0^+ \times \Omega$. Then $w_2 > -\infty$, as shown in the first part of Theorem 3.1. Assume also that $Eu(0) < E_1$. We first claim that $v_1 \notin \overline{v(\mathbb{R}_0^+)}$. Proceed by contradiction and suppose that $v_1 \in \overline{v(\mathbb{R}_0^+)}$. It follows that there exists a sequence $(t_j)_j$ in \mathbb{R}_0^+ such that $v(t_j) \rightarrow v_1$ as $j \rightarrow \infty$. By (4.11) we have $E_1 > Eu(0) \geq Eu(t_j) \geq \varphi(v(t_j))$, which provides $E_1 > E_1$ by the continuity of $\varphi \circ v$, and the claim is proved.

We show that $w_2 \neq \gamma p_+ w_1 / q_-$. Otherwise, $\mathcal{F}u(t) \geq \gamma p_+ w_1 / q_-$ for all $t \in \mathbb{R}_0^+$. Therefore, by (3.1) and (4.13), we have

$$\left(\frac{q_-}{\gamma p_+} - 1 \right) \mathcal{F}u(t) \geq E_1 > Eu(0) \geq \mathcal{A}u(t) - \mathcal{F}u(t),$$

so that, using (4.6) and (4.10), for each $t \in \mathbb{R}_0^+$ we get

$$\frac{c}{\gamma p_+} \rho_{q(\cdot)}(u(t, \cdot)) \geq \frac{q_-}{\gamma p_+} \mathcal{F}u(t) > \mathcal{A}u(t) \geq \frac{s}{(\Lambda p_+)^{\gamma}} \min \{v(t)^{p_-}, v(t)^{p_+}\}^{\gamma}.$$

Hence, if $t \in \mathbb{R}_0^+$ and $v(t) \leq 1$, then $cv(t)^{q-}/\gamma p_+ > sv(t)^{\gamma p_+}/(\Lambda p_+)^{\gamma}$ using also (2.1), that is $v(t) > v_1$. On the other hand, if $v(t) > 1$, then automatically $v(t) > v_1$, being $v_1 \leq 1$. Hence, $v(t) > v_1$ for each $t \in \mathbb{R}_0^+$, so that by (4.10), we immediately obtain $\mathcal{A}u(t) > w_1$ for all $t \in \mathbb{R}_0^+$, where w_1 is defined in (4.13). Consequently, $\mathcal{F}u(t) \geq w_1 - Eu(0) > w_1 - E_1 = \gamma p_+ w_1/q_-$ for all $t \in \mathbb{R}_0^+$ and in turn $w_2 > \gamma p_+ w_1/q_-$. This gives an obvious contradiction.

Suppose that $w_2 > \gamma p_+ w_1/q_-$. We prove that $v(\mathbb{R}_0^+) \subset (v_1, \infty)$, which immediately gives $\overline{v(\mathbb{R}_0^+)} \subset (v_1, \infty)$, since $v_1 \notin \overline{v(\mathbb{R}_0^+)}$. Assume by contradiction that there exists $t_1 \in \mathbb{R}_0^+$ for which $v(t_1) \leq v_1$. It follows

$$\mathcal{F}u(t_1) \leq \frac{c}{q_-} v(t_1)^{q-} \leq \frac{c}{q_-} v_1^{q-} = \frac{\gamma p_+}{q_-} w_1,$$

so that $w_2 \leq \gamma p_+ w_1/q_-$, which is impossible.

On the other hand, if $v(\mathbb{R}_0^+) \subset (v_1, \infty)$, then $v(t) > v_1$ for all $t \in \mathbb{R}_0^+$. Hence $\mathcal{F}u(t) \geq w_1 - Eu(0) > w_1 - E_1 = \gamma p_+ w_1/q_-$ for all $t \in \mathbb{R}_0^+$ by (3.1) and in turn $w_2 > \gamma p_+ w_1/q_-$, as required. \square

In the next corollary we present an application of both Theorems 3.1 and 4.1. In particular, we provide sufficient conditions under which assumptions (3.6)–(3.7) of Theorem 3.1 are satisfied. Let $Q = Q(t, x, u, v)$ be a continuous damping function as in the Section 1 and assume also that there exists $t^* \gg 1$ such that for all $(t, x, u, v) \in [t^*, \infty) \times \Omega \times \mathbb{R}^N \times \mathbb{R}^N$

$$Q(t, x, u, v) = d(t, x)|u|^\kappa |v|^{m-2}v, \tag{4.16}$$

where $\kappa \geq 0$, $m > 1$, $m + \kappa < q_-$, $d \in C(\mathbb{R}_0^+ \rightarrow L^{q_-/(q_- - \kappa - m)}(\Omega))$, with $d(t, x) \geq 0$ in $\mathbb{R}_0^+ \times \Omega$. Put $\delta(t) = \|d(t, \cdot)\|_{q_-/(q_- - \kappa - m)}$. Hence,

$$|Q(t, x, u, v)| = [d(t, x)|u|^\kappa]^{1/m} [(Q(t, x, u, v), v)]^{1/m'}$$

for all $(t, x, u, v) \in [t^*, \infty) \times \Omega \times \mathbb{R}^N \times \mathbb{R}^N$, so that (Q_1) holds with $t_Q = t^*$. Now put $J = [t^*, \infty)$.

Corollary 4.1. Assume (4.1)–(4.3), (4.16) and that $\delta(t) \leq \delta_1(1 + t)^\ell$ for each $t \in J$, for some appropriate numbers $\delta_1 \geq 1$ and $\ell \leq m - 1$. Then there are no solutions $u \in K$ of (1.1) in $\mathbb{R}_0^+ \times \Omega$, with $Eu(0) < \tilde{E}_1$.

Proof. Let $u \in K$ be a solution of (1.1) in $\mathbb{R}_0^+ \times \Omega$, with $Eu(0) < \tilde{E}_1$. All the structural assumptions of Theorem 4.1 are available, and it remains to provide the auxiliary functions k and ψ verifying (3.6), with θ_0 as in (3.7) to reach the desired contradiction.

Take $k(t) \equiv \delta_1^{m'}$ and $\psi(t) = \delta_1(1 + t)^{-\ell/(m-1)}$ for each $t \in J$, so that (3.6)₁ is verified in J . If $\ell \geq 0$, then $k(t) \geq \psi(t)$ for each $t \in J$, being $\delta_1 \geq 1$. Otherwise, if $\ell < 0$, take $S_0 \geq \max\{t^*, \delta_1^{1/|\ell|} - 1\}$ so that for all $t \geq S_0$

$$\psi(t) \geq \psi(S_0) = \delta_1(1 + S_0)^{|\ell|/(m-1)} \geq \delta_1^{m'} = k(t).$$

Hence, for each $t \geq S_0$ we have

$$\psi(t)[\max\{k(t), \psi(t)\}]^{-(1+\theta)} = \begin{cases} \delta_1^{1-m'(1+\theta)}(1+t)^{-\ell/(m-1)}, & \text{if } \ell \geq 0, \\ \delta_1^{-\theta}(1+t)^{\ell\theta/(m-1)}, & \text{if } \ell < 0. \end{cases}$$

Clearly (3.6)₂ is verified for all $\theta \in (0, \theta_0)$, with θ_0 as in (3.7), whenever $\ell \geq 0$ since $\ell \leq m - 1$. While, if $\ell < 0$, then we choose $\theta \in (0, \theta_0)$, so small that $\theta \leq (m - 1)/|\ell|$, that is so small that (3.6)₂ holds. \square

Observe that even in the case $\ell < 0$ the function δ in Corollary 4.1 does not need to be non-increasing in $[S_0, \infty)$, as the function $\delta(t) = \delta_1|\sin t|(1+t)^\ell$ shows. As a matter of fact, δ obviously verifies the relation $\delta(t) \leq \delta_1(1+t)^\ell$, but it approaches zero as $t \rightarrow \infty$ oscillating.

From now on in the section we assume for simplicity the structure assumptions (4.1)–(4.3) and (4.16), with $\delta(t) \leq \delta_1(1+t)^\ell$ for each $t \in J$ and some $\delta_1 \geq 1$, with $\ell \leq m - 1$.

The following corollary extends and generalizes Theorems 5 and 6 of [17], the first part of Theorem 4 of [23] and Theorem 3.1 of [24], and Theorems 4.3 and 4.5 of [25].

Corollary 4.2. *Problem (1.1) does not possess solutions $u \in K$ in $\mathbb{R}_0^+ \times \Omega$, with*

$$\|u(0, \cdot)\|_{q(\cdot)} > v_1, \quad Eu(0) < E_1, \tag{4.17}$$

where E_1 is defined in (4.13).

Proof. Assume by contradiction that $u \in K$ is a solution of (1.1) in $\mathbb{R}_0^+ \times \Omega$, verifying (4.17). By Theorem 4.2 then $w_2 > \gamma p_+ w_1/q_-$. Hence $Eu(0) < E_1 < \tilde{E}_1$ and the contradiction follows at once by an application of Corollary 4.1. \square

Proposition 4.1. *If $u \in K$ is a solution of (1.1) in $\mathbb{R}_0^+ \times \Omega$, with $Eu(0) \leq E_1$, where E_1 is defined in (4.13), then*

$$w_2 \leq \frac{\gamma p_+}{q_-} w_1. \tag{4.18}$$

Proof. Otherwise $w_2 > \gamma p_+ w_1/q_-$, so that $Eu(0) < \tilde{E}_1$, and u could not be global by Corollary 4.1. \square

In the sequel of the section we assume also

(\mathcal{D}) *There exists $t_* > 0$ such that either*

- (i) $g_t(t, x) \geq g_0(t) > 0$ for each $(t, x) \in [0, t_*] \times \Omega$, or
- (ii) $\phi \in K$ and $\langle Q(t, \cdot, \phi, \phi_t), \phi_t \rangle = 0$ in $[0, t_*]$ implies either $\phi(t, \cdot) \equiv 0$ or $\phi_t(t, \cdot) \equiv 0$ for all $t \in [0, t_*]$,

which allows us to extend and generalizes the second part of Theorems 4 of [23] and 3.1 of [24].

Theorem 4.3. *Problem (1.1) does not possess solutions $u \in K$ in $\mathbb{R}_0^+ \times \Omega$, with*

$$\|u(0, \cdot)\|_{q(\cdot)} > v_1, \quad Eu(0) = E_1. \tag{4.19}$$

Proof. Assume by contradiction that $u \in K$ is a global solution of (1.1) in $\mathbb{R}_0^+ \times \Omega$, verifying (4.19). By Proposition 4.1 we have $w_2 \leq \gamma p_+ w_1 / q_-$. We first claim that $w_2 < \gamma p_+ w_1 / q_-$ cannot occur. Otherwise there exists t_0 such that $\mathcal{F}u(t_0) < \gamma p_+ w_1 / q_-$, so that by (B)-(ii) and (3.1)

$$w_1 - \mathcal{F}u(t_0) > E_1 = Eu(0) \geq Eu(t_0) \geq \mathcal{A}u(t_0) - \mathcal{F}u(t_0),$$

and by (4.10), (4.12) and (4.13) it is not hard to see that $v(t_0) < v_1$. Hence $t_0 > 0$ by (4.19) and by the continuity of v there exists $s \in (0, t_0)$ such that $v(s) = v_1$. The above argument and (4.6) show that $E_1 = Eu(0) \geq Eu(s) \geq w_1 - cv_1^{q_-} / q_- = E_1$. In other words, $Eu(s) = E_1$ and $\int_0^s \mathcal{D}u(\tau) d\tau = 0$ by (B)-(ii). Consequently $\mathcal{D}u \equiv 0$ in $[0, s]$ and so, by (\mathcal{F}_2) and (4.16), we obtain $\langle Q(t, \cdot, u(t, \cdot), u_t(t, \cdot)), u_t(t, \cdot) \rangle = 0$ and $\mathcal{F}_t u(t) = 0$ for all $t \in [0, s]$.

Now, if (\mathcal{D}) -(i) holds, then

$$0 = \mathcal{F}_t u(t) = \int_{\Omega} g_t(t, x) \frac{|u(t, x)|^{\sigma(x)}}{\sigma(x)} dx \geq \frac{g_0(t)}{\sigma_+} \rho_{\sigma(\cdot)}(u(t, \cdot)) \geq 0$$

for each $t \in [0, s_0]$, where $s_0 = \min\{t_*, s\}$. Therefore $\rho_{\sigma(\cdot)}(u(t, \cdot)) \equiv 0$ and in turn $u \equiv 0$ in $[0, s_0] \times \Omega$, by (2.1). But this occurrence is impossible, since $\|u(0, \cdot)\|_{q(\cdot)} = v(0) > v_1 > 0$ by (4.19)₁, so that we reach a contradiction.

While, if (\mathcal{D}) -(ii) holds, since $\langle Q(t, \cdot, u(t, \cdot), u_t(t, \cdot)), u_t(t, \cdot) \rangle = 0$ for all $t \in [0, s_0]$, we get that either $u(t, \cdot) = 0$ or $u_t(t, \cdot) = 0$ for all $t \in [0, s_0]$, where as above $s_0 = \min\{t_*, s\}$. Again, as already shown, the first case cannot occur since $v(0) > v_1$. In the latter, u is clearly constant with respect to t in $[0, s_0]$, and so $u(t, x) = u(0, x)$ for each $t \in [0, s_0]$. Taking $\phi(t, x) = u(0, x)$ in the *Distribution Identity* (A), then for each $t \in [0, s_0]$ we have $t \langle Au(0, \cdot), u(0, \cdot) \rangle = \int_0^t \langle f(\tau, \cdot, u(0, \cdot)), u(0, \cdot) \rangle d\tau$, since $\langle Q(t, \cdot, u(0, \cdot), 0), u(0, \cdot) \rangle = 0$ by (4.8), being $\mathcal{D}u = 0$ in $[0, s_0]$. Therefore $\langle Au(0, \cdot), u(0, \cdot) \rangle = \langle f(t, \cdot, u(0, \cdot)), u(0, \cdot) \rangle$ for each $t \in [0, s_0]$, and so $\langle A(u(0, \cdot)), u(0, \cdot) \rangle = \langle f(0, \cdot, u(0, \cdot)), u(0, \cdot) \rangle$. Now $\gamma p_+ \mathcal{A}u(0) \geq q_- \mathcal{F}u(0)$ by (3.3) and (\mathcal{F}_3) . On the other hand, $E_1 = Eu(0) = \mathcal{A}u(0) - \mathcal{F}u(0)$ by (3.1), since $u_t(0, \cdot) = 0$. By (4.15) and (4.13) we have $\mathcal{A}u(0) > w_1 > 0$, and so

$$E_1 \geq \left(1 - \frac{\gamma p_+}{q_-}\right) \mathcal{A}u(0) > \left(1 - \frac{\gamma p_+}{q_-}\right) w_1 = E_1$$

by (4.13). This contradiction shows the claim.

Hence $w_2 = \gamma p_+ w_1 / q_-$. In particular $\mathcal{F}u(t) \geq \gamma p_+ w_1 / q_-$ for all $t \in \mathbb{R}_0^+$ and we assert that equality cannot occur at a finite time. Indeed, if there is s such that $\mathcal{F}u(s) = \gamma p_+ w_1 / q_-$, then $v(s) \geq v_1$ by (4.6) and (2.1). But $v(s) > v_1$ would imply $Eu(0) > E_1$, contradicting (4.19). Hence $\mathcal{F}u(s) = \gamma p_+ w_1 / q_-$, $v(s) = v_1$ and so $Eu(s) = E_1$. From now on we can repeat the argument above in correspondence at such s and assumption (\mathcal{D}) will produce the required contradiction again.

Therefore it remains to consider the case $w_2 = \gamma p_+ w_1 / q_-$, $\mathcal{F}u(t) > w_2$ and $v(t) > v_1$ for all $t \in \mathbb{R}_0^+$. A continuity argument shows at once that

$$\liminf_{t \rightarrow \infty} \mathcal{F}u(t) = w_2.$$

On the other hand by (3.1) and (B)-(ii) we have $w_1 - \mathcal{F}u(t) < Eu(t) \leq E_1$, so that $\limsup_{t \rightarrow \infty} Eu(t) = E_1$. Hence $\int_0^\infty \mathcal{D}u(\tau) d\tau = 0$ by monotonicity. In particular $\mathcal{D}u \equiv 0$ in \mathbb{R}_0^+ , which is again impossible by (\mathcal{D}) using the argument already produced. This completes the proof. \square

Remark 4.1. The possibility to cover the case (4.19) was first discovered by VITILLARO [23], but only for *strong* solutions. Indeed, to cover (4.19) in [23,24] the energy conservation law was considered with the equality sign, as in (B)_s-(ii), even if not explicitly stated, as for example, in the proof of case (a) of Theorem 3 of [23]. Furthermore, in [23,24] essentially the autonomous case was treated. It is interesting to note that Theorems 3 and 4 of [23] covers only the case when $Q > 0$ near 0, while in Theorem 5.4 we are able to consider even the situation in which $Q \equiv 0$, provided that (\mathcal{D}) -(i) is valid. The proof of Theorem 4.3 differs from that of Theorems 3 and 4 of [23], being based on Proposition 4.1 and on Theorem 3.1.

Appendix: The linear dissipation case

In this section we provide a non-continuation result for (1.1) when (\mathcal{F}_1) and (\mathcal{F}_2) hold as in Section 3, while (\mathcal{F}_3) is replaced by a weaker condition provided that the damping term is linear, that is $Q(t, x, u, v) = Q(t)v$. More precisely, (1.1) reduces simply to

$$\begin{cases} u_{tt} - M(\mathcal{J}u(t)) \Delta_{p(x)}u + \mu|u|^{p(x)-2}u + Q(t)u_t = f(t, x, u), \\ u(t, x) = 0 \quad \text{on } \mathbb{R}_0^+ \times \partial\Omega, \end{cases} \quad (5.1)$$

where as before $u = (u_1, \dots, u_N) = u(t, x)$ is the vectorial displacement, $N \geq 1$, the domain Ω is bounded in \mathbb{R}^n and $\mu \geq 0$. In place of (Q) we assume throughout the section the stronger condition

$$(Q) \quad Q \in C^1(\mathbb{R}_0^+), \quad \text{with } Q, -Q' \geq 0,$$

which indeed implies (Q_1) , see the next Remark 5.1.

The function space K is given in Section 2, while $E\phi$, $\mathcal{A}\phi$ and $A\phi$, with $\phi \in K$, are the same functions introduced in (3.1) and (3.2). As in Section 3 we define a solution of (5.1) as a function $u \in K$ satisfying the two conditions:

(A) *Distribution Identity*

$$\begin{aligned} \langle u_t, \phi \rangle \Big|_0^t &= \int_0^t \{ \langle u_\tau, \phi_t \rangle - M(\mathcal{J}u(\tau)) \langle |Du|^{p(\cdot)-2} Du, D\phi \rangle \\ &\quad - \mu \langle |u|^{p(\cdot)-2} u, \phi \rangle - \langle Q(\tau)u_t - f, \phi \rangle \} d\tau \end{aligned}$$

for all $t \in \mathbb{R}_0^+$ and $\phi \in K$;

(B) *Energy Conservation*

$$Eu(t) \leq Eu(0) - \int_0^t \left\{ Q(\tau) \|u_\tau(\tau, \cdot)\|_2^2 + \mathcal{F}_t u(\tau) \right\} d\tau$$

for all $t \in \mathbb{R}_0^+$.

By (\mathcal{F}_1) , (\mathcal{F}_2) and (Q) properties (A) and (B) are meaningful. Instead of (\mathcal{F}_3) here we assume the weaker assumption: *there exists $q \in C_+(\bar{\Omega})$, satisfying (3.4), such that*

$$(\mathcal{F}_3)' \quad \langle f(t, \cdot, \phi(t, \cdot)), \phi(t, \cdot) \rangle \geq q_- \mathcal{F} \phi(t) \quad \text{for } (t, \phi) \in \mathbb{R}_0^+ \times K.$$

See (4.4).

Theorem 5.1. *Suppose that (\mathcal{M}) , (Q) , (\mathcal{F}_1) and (\mathcal{F}_2) hold true. If $u \in K$ is a solution of (5.1) in $\mathbb{R}_0^+ \times \Omega$, then $w_2 = \inf_{t \in \mathbb{R}_0^+} \mathcal{F}u(t) > -\infty$.*

Finally, assume that $2 < \gamma p_+$ and also that $(\mathcal{F}_3)'$ is satisfied. Then there are no solutions $u \in K$ of (5.1) in $\mathbb{R}_0^+ \times \Omega$, with $Eu(0) < \tilde{E}_1$, where \tilde{E}_1 is defined in (3.5).

Proof. The first part of the result is just a direct consequence of Theorem 3.1, since clearly here $(Q(t)v, v) = Q(t)|v|^2 \geq 0$ for all $(t, v) \in \mathbb{R}_0^+ \times \mathbb{R}^N$.

Assume now that $2 < \gamma p_+$ and also $(\mathcal{F}_3)'$ holds, and by contradiction that there exists a solution $u \in K$ of (5.1) in $\mathbb{R}_0^+ \times \Omega$, with $Eu(0) < \tilde{E}_1$. Then $w_2 > 0$ and $\tilde{E}_1 > 0$ by virtue of (3.4) and (3.5). Define in \mathbb{R}_0^+

$$\begin{aligned} \mathcal{G}(t) &= \|u(t, \cdot)\|_2^2 + \int_0^t \{Q(\tau)\|u(\tau, \cdot)\|_2^2 + (\tau - t)Q'(\tau)\|u(\tau, \cdot)\|_2^2\} d\tau \\ &\quad + (T_0 - t)Q(0)\|u(0, \cdot)\|_2^2 + \beta(t + \beta_0)^2, \end{aligned}$$

where $T_0, \beta, \beta_0 > 0$ are constants which will be fixed later. Since $Q \in C^1(\mathbb{R}_0^+)$, it results

$$\begin{aligned} \mathcal{G}'(t) &= 2\langle u(t, \cdot), u_t(t, \cdot) \rangle + Q(t)\|u(t, \cdot)\|_2^2 - Q(0)\|u(0, \cdot)\|_2^2 \\ &\quad - \int_0^t Q'(\tau)\|u(\tau, \cdot)\|_2^2 d\tau + 2\beta(t + \beta_0) \\ &= 2\langle u(t, \cdot), u_t(t, \cdot) \rangle + 2 \int_0^t Q(\tau)\langle u(\tau, \cdot), u_t(\tau, \cdot) \rangle d\tau + 2\beta(t + \beta_0). \end{aligned}$$

From the *Distribution Identity* (A), taking $\phi = u \in K$, it follows that

$$\begin{aligned} \frac{1}{2} \mathcal{G}''(t) &= \|u_t(t, \cdot)\|_2^2 - Q(t)\langle u_t(t, \cdot), u(t, \cdot) \rangle - \langle Au(t, \cdot), u(t, \cdot) \rangle \\ &\quad + \langle f(t, \cdot, u(t, \cdot)), u(t, \cdot) \rangle + Q(t)\langle u(t, \cdot), u_t(t, \cdot) \rangle + \beta \\ &= \|u_t(t, \cdot)\|_2^2 - \langle Au(t, \cdot), u(t, \cdot) \rangle + \langle f(t, \cdot, u(t, \cdot)), u(t, \cdot) \rangle + \beta. \end{aligned}$$

Now observe that, thanks to (3.3) and $(\mathcal{F}_3)'$, we have

$$\langle Au(t, \cdot), u(t, \cdot) \rangle - \langle f(t, \cdot, u(t, \cdot)), u(t, \cdot) \rangle \leq \gamma p_+ \mathcal{A}u(t) - q_- \mathcal{F}u(t).$$

Hence, combining these formulas with the definition (3.1) of the energy function, we get

$$\begin{aligned} \frac{1}{2} \mathcal{G}''(t) &\geq \|u_t(t, \cdot)\|_2^2 - \gamma p_+ \mathcal{A}(u) + q_- \mathcal{F}u(t) + \beta \\ &= \left(1 + \frac{\gamma p_+}{2}\right) \|u_t(t, \cdot)\|_2^2 + (q_- - \gamma p_+) \mathcal{F}u(t) \\ &\quad - \gamma p_+ Eu(t) + \beta. \end{aligned} \tag{5.2}$$

Now $(q_- - \gamma p_+) \mathcal{F}u(t) \geq (q_- - \gamma p_+) w_2 = \gamma p_+ \tilde{E}_1$ by (3.5), and also $Eu(t) \leq Eu(0) - \int_0^t Q(\tau) \|u_t(\tau, \cdot)\|_2^2 d\tau$ by the *Energy Conservation* (B) and (\mathcal{F}_2) . Therefore

$$\mathcal{G}''(t) \geq (2 + \gamma p_+) \left\{ \|u_t(t, \cdot)\|_2^2 + \beta \right\} + 2\gamma p_+ \int_0^t Q(\tau) \|u_t(\tau, \cdot)\|_2^2 d\tau, \tag{5.3}$$

where $\beta = 2\{\tilde{E}_1 - Eu(0)\} > 0$ by (3.5). Take β_0 so large that $\mathcal{G}'(0) = 2\langle u(0, \cdot), u_t(0, \cdot) \rangle + 2\beta\beta_0 > 0$. Then, since Q is non-negative in \mathbb{R}_0^+ , it results

$$\mathcal{G}'', \mathcal{G}', \mathcal{G} > 0 \text{ in } \mathbb{R}_0^+.$$

We assert that

$$\mathcal{G} \mathcal{G}'' - \alpha \mathcal{G}'^2 \geq 0 \text{ in } [0, T_0], \tag{5.4}$$

for any $T_0 > 0$, where $\alpha = (2 + \gamma p_+)/4$. Put

$$\mathbb{A} = \|u(t, \cdot)\|_2^2 + \int_0^t Q(\tau) \|u(\tau, \cdot)\|_2^2 d\tau + \beta(t + \beta_0)^2,$$

$\mathbb{B} = \frac{1}{2} \mathcal{G}'$ and $\mathbb{C} = \|u_t(t, \cdot)\|_2^2 + \int_0^t Q(\tau) \|u_t(\tau, \cdot)\|_2^2 d\tau + \beta$. Since Q and $-Q'$ are non-negative in \mathbb{R}_0^+ by (Q) , we have

$$\mathbb{A} \leq \mathcal{G} \text{ in } [0, T_0]. \tag{5.5}$$

Moreover, by (5.3) and the fact that $2\gamma p_+ > \gamma p_+ + 2$, being $\gamma p_+ > 2$, we get

$$\mathbb{C} \leq \mathcal{G}'' / (2 + \gamma p_+) \text{ in } \mathbb{R}_0^+. \tag{5.6}$$

Observe that for all $(\xi, \eta) \in \mathbb{R}^2$ and $t \in \mathbb{R}_0^+$

$$\begin{aligned} \mathbb{A}\xi^2 + 2\mathbb{B}\xi\eta + \mathbb{C}\eta^2 &= \|\xi u(t, \cdot) + \eta u_t(t, \cdot)\|_2^2 + \int_0^t Q(\tau) \|\xi u(\tau, \cdot) \\ &\quad + \eta u_t(\tau, \cdot)\|_2^2 d\tau + \beta \{(t + \beta_0)\xi + \eta\}^2 \geq 0, \end{aligned}$$

because Q is non-negative in \mathbb{R}_0^+ . Thus $\mathbb{A}\mathbb{C} - \mathbb{B}^2 \geq 0$. Hence, (5.4) holds by virtue of (5.5), (5.6) and the fact that $\mathbb{A}, \mathbb{C} > 0$.

Clearly $\alpha > 1$ since $\gamma p_+ > 2$ by assumption. Now (5.4) can be written as $(\mathcal{G}^{-\alpha} \mathcal{G}')' \geq 0$, so that

$$\frac{\mathcal{G}'(t)}{\mathcal{G}^\alpha(t)} \geq \frac{\mathcal{G}'(0)}{\mathcal{G}^\alpha(0)} > 0 \text{ for } t \in [0, T_0].$$

This is a Riccati inequality with blow up time

$$T < \frac{1}{\alpha - 1} \cdot \frac{\mathcal{G}(0)}{\mathcal{G}'(0)}. \tag{5.7}$$

Consequently, if T_0 is chosen as the right-hand side of the above inequality we have a contradiction. In fact, since $\mathcal{G}(0)$ depends linearly on T_0 , this gives an easily solved equation for T_0 , the solution being positive for all β_0 large enough, for example, whenever

$$\beta\beta_0 > \frac{2}{\gamma p_+ - 2} Q(0)\|u(0, \cdot)\|_2^2 - \langle u(0, \cdot), u_t(0, \cdot) \rangle,$$

where $\beta = 2\{\tilde{E}_1 - Eu(0)\} > 0$. This completes the proof. \square

Remark 5.1. *The next result gives new information only when $\gamma p_+ \leq 2$ and (\mathcal{F}_3) does not hold. Otherwise it is a strict consequence of either Theorem 5.1 when $\gamma p_+ > 2$ or Theorem 3.1 if (\mathcal{F}_3) holds. Indeed, for linear damping functions, satisfying (Q) , condition (Q_1) of Section 4 is verified, with $m = 2, \kappa = 0$ and $\delta(t) = |\Omega|^{(q_- - 2)/q_-} Q(t)$, and so (Q) holds. Furthermore, in Theorem 3.1 we can choose $\psi = 1$ and $k = \max\{|\Omega|^{(q_- - 2)/q_-} Q(0), 1\}$, so that (3.6) is automatic for any $\theta \in (0, \theta_0)$, where now $\theta_0 = (q_- - 2)/(q_- + 2)$.*

However, Theorem 5.1 is not completely contained in Theorem 3.1, since $(\mathcal{F}_3)'$ is weaker than (\mathcal{F}_3) -(ii) even when (\mathcal{F}_3) -(i) holds, as the example (4.1), (4.2) shows. Indeed, any function f verifying (4.1), (4.2) satisfies $(\mathcal{F}_1), (\mathcal{F}_2), (\mathcal{F}_3)'$ and (\mathcal{F}_3) -(i), but not in general (\mathcal{F}_3) -(ii), when (4.3) does not hold; while the validity of (4.1)–(4.3) implies (4.4), which is exactly $(\mathcal{F}_3)'$.

We note in passing that even for linear damping the case $(\mathcal{F}_3)'$ was not covered in [23–25], while first appears in [22].

Theorem 5.2. *Suppose that $(\mathcal{M}), (Q), (\mathcal{F}_1), (\mathcal{F}_2)$ and $(\mathcal{F}_3)'$ hold. Then there are no solutions $u \in K$ of (5.1) in $\mathbb{R}_0^+ \times \Omega$, satisfying (3.21).*

Proof. Assume by contradiction that there exists a solution $u \in K$ of problem (5.1) in $\mathbb{R}_0^+ \times \Omega$, satisfying (3.21). Define in \mathbb{R}_0^+ the same function \mathcal{G} as in Theorem 5.1, obtaining in place of (5.2) the estimate

$$\mathcal{G}''(t) \geq (2 + q_-) \|u_t(t, \cdot)\|_2^2 + 2(q_- - \gamma p_+) \mathcal{A}u(t) - 2q_- Eu(t) + 2\beta.$$

Using the fact that $(q_- - \gamma p_+) \mathcal{A}u(t) \geq (q_- - \gamma p_+) w_1 = q_- E_1$ by (3.21), from the previous relation, in place of (5.3), we get

$$\mathcal{G}''(t) \geq (2 + q_-) \left\{ \|u_t(t, \cdot)\|_2^2 + \beta \right\} + 2q_- \int_0^t Q(\tau) \|u_t(\tau, \cdot)\|_2^2 d\tau, \quad (5.8)$$

where now $\beta = 2\{E_1 - Eu(0)\} > 0$. From here on the proof is the same as that of Theorem 5.1, with q_- in place of γp_+ and $\alpha = (2 + q_-)/4$. Again $\alpha > 1$, since $q_- > 2$ by (3.4). \square

Remark 5.2. In all Theorems 3.1, 5.1 and 5.2, as well as in their consequences, the trivial case $Q \equiv 0$ can be included.

It is clear from the proofs of Theorems 5.1 and 5.2 that it is possible to find an upper bound for the blow up time T by virtue of (5.7). Indeed, by the choice of β_0

$$T_0 = \frac{\|u(0, \cdot)\|_2^2 + \beta\beta_0^2}{2(\alpha - 1)(\beta\beta_0 - a_0)}, \quad a_0 = \frac{Q(0)\|u(0, \cdot)\|_2^2}{2(\alpha - 1)} - \langle u(0, \cdot), u_t(0, \cdot) \rangle,$$

where $\alpha = (2 + \gamma p_+)/4 > 1$, $\beta = 2\{\tilde{E}_1 - Eu(0)\} > 0$ in Theorem 5.1, while $\alpha = (2 + q_-)/4 > 1$, $\beta = 2\{E_1 - Eu(0)\} > 0$ in Theorem 5.2. Similar results were given in [25, Theorem 3.4], when $Q \equiv 1$.

It is worth noting that *in the standard degenerate Kirchhoff case in which $p \equiv 2$ and $\gamma > 1$, the restriction $2 < \gamma p_+$ is automatic*. Hence Theorem 5.1 fits fairly well in the main prototype of the paper.

As a natural application of Theorems 5.1 and 5.2 and of Remark 5.1 *from now on we assume the validity of (4.1) and (4.2) on f and M* . As in Section 4 we distinguish two cases, depending on whether b is zero or not. Let $s = b$ and $\gamma > 1$ if $b > 0$, while $s = a$ and $\gamma = 1$ if $b = 0$. Of course we are much more interested in the *degenerate case* $a = 0$, when an effective Kirchhoff term arises in the system. Lemma 4.3 and Theorem 4.2 continue to hold and consequently (4.10)–(4.13) are still available.

Theorem 5.3. *If $u \in K$ is a solution of problem (5.1) in $\mathbb{R}_0^+ \times \Omega$, then $w_2 = \inf_{t \in \mathbb{R}_0^+} \mathcal{F}u(t) > -\infty$. If, in addition, $Eu(0) < \tilde{E}_1$, with \tilde{E}_1 given as in (3.5), then $w_2 > 0$, $\tilde{E}_1 > 0$ and $(v(t), Eu(t)) \in \tilde{\Sigma}$ for all $t \in \mathbb{R}_0^+$, where $\tilde{\Sigma}$ is defined in (4.14).*

There are no solutions $u \in K$ of (5.1) in $\mathbb{R}_0^+ \times \Omega$, if either $2 < \gamma p_+$ and $Eu(0) < \tilde{E}_1$, or $\gamma p_+ \leq 2$ and $Eu(0) < E_1$.

Proof. The first part is a consequence of the first part of Theorem 5.1. The second part can be proved exactly as in Theorem 4.1, using (B) in place of (B)-(ii). The last part of the result is now a direct consequence of either Theorem 5.1 or Theorem 5.2. □

Corollary 5.1. *If $u \in K$ is a solution of (5.1) in $\mathbb{R}_0^+ \times \Omega$, with $Eu(0) \leq E_1$, then (4.18) holds provided that $2 < \gamma p_+$.*

While there are no solutions $u \in K$ of (5.1) in $\mathbb{R}_0^+ \times \Omega$ when (4.17) holds.

Proof. Both statements can be proved exactly as Proposition 4.1 and Corollary 4.2 using Theorem 5.3 in place of Corollary 4.1. □

In this context condition (D)-(ii) of Section 4 reduces simply to the request that $Q > 0$ in $[0, t_*)$.

Theorem 5.4. *If $2 < \gamma p_+$ and also (D) holds, then problem (5.1) does not possess solutions $u \in K$ in $\mathbb{R}_0^+ \times \Omega$, satisfying (4.19).*

Proof. The proof is exactly as for Theorem 4.3, with the use of the first part of Corollary 5.1 instead of Proposition 4.1. □

As in Section 3 we say that $u \in K$ is a *strong solution* of (5.1) if u satisfies the *Distribution Identity* (A), while (B) is replaced by the *Strong Energy Conservation* (B)_s, that is $Eu(t) = Eu(0) - \int_0^t \{Q(\tau)\|u_\tau(\tau, \cdot)\|_2^2 + \mathcal{F}_\tau u(\tau)\} d\tau$ for all $t \in \mathbb{R}_0^+$. We already noted in Section 3 the importance to consider (weak) solutions.

Theorem 5.5. *If $2 \geq \gamma p_+$ and also (D) holds, then problem (5.1) does not possess strong solutions $u \in K$ in $\mathbb{R}_0^+ \times \Omega$, satisfying (4.19).*

Proof. Assume by contradiction that $u \in K$ is a strong solution in $\mathbb{R}_0^+ \times \Omega$ of (5.1), satisfying (4.19). First we prove that there are no points $s > 0$ such that $v(s) = v_1$. Otherwise $Eu(s) = E_1$ and, as shown in the proof of Theorem 4.3, assumption (D) would provide a contradiction. Hence $v(t) > v_1$ and $Eu(t) < E_1$ for all $t > 0$ by an obvious continuity argument and (B)_s. In particular, this implies (4.15). Now fix $t_0 > 0$, so that

$$\inf_{t \in \mathbb{R}_0^+} \mathcal{A}u(t) \geq w_1 \quad \text{and} \quad Eu(t_0) < E_1, \tag{5.9}$$

where w_1 and E_1 are given in (4.13). Put $I = [t_0, \infty)$ and define for $t \in I$,

$$\begin{aligned} \mathcal{G}(t) &= \|u(t, \cdot)\|_2^2 + \int_{t_0}^t \left\{ Q(\tau)\|u(\tau, \cdot)\|_2^2 + (\tau - t)Q'(\tau)\|u(\tau, \cdot)\|_2^2 \right\} d\tau \\ &\quad + (T_0 + t_0 - t)Q(t_0)\|u(t_0, \cdot)\|_2^2 + \beta(t - t_0 + \beta_0)^2, \end{aligned}$$

where $T_0, \beta, \beta_0 > 0$ are constants which will be fixed later. We proceed almost exactly as in the proof of Theorem 5.2 until (5.8), with the obvious changes. Now $Eu(t) \leq Eu(t_0) - \int_{t_0}^t Q(\tau)\|u_\tau(\tau, \cdot)\|_2^2 d\tau$ by the *Energy Conservation* (B)_s and (F)₂, so that (5.8) is replaced by

$$\mathcal{G}''(t) \geq (2 + q_-) \left\{ \|u_t(t, \cdot)\|_2^2 + \beta \right\} + 2q_- \int_{t_0}^t Q(\tau)\|u_\tau(\tau, \cdot)\|_2^2 d\tau,$$

where now $\beta = 2\{E_1 - Eu(t_0)\} > 0$ by (5.9). Condition (5.4) holds in $[t_0, t_0 + T_0]$, where $\alpha = (2 + q_-)/4$ as in Theorems 5.2. But u cannot be global as in the proofs of Theorems 5.1 and 5.2, by taking $\beta_0 > 0$ so large that

$$\beta\beta_0 > \frac{2}{q_- - 2} Q(t_0)\|u(t_0, \cdot)\|_2^2 - \langle u(t_0, \cdot), u_t(t_0, \cdot) \rangle,$$

while

$$T_0 = \frac{4}{q_- - 2} \cdot \frac{\mathcal{G}(t_0)}{\mathcal{G}'(t_0)},$$

since again $\mathcal{G}(t_0)$ depends linearly on T_0 and the equation is solvable in T_0 thanks to the choice of β_0 . Here clearly $\mathbb{A} = \|u(t, \cdot)\|_2^2 + \int_{t_0}^t Q(\tau)\|u(\tau, \cdot)\|_2^2 d\tau + \beta(t - t_0 + \beta_0)^2$, then $\mathbb{B} = \frac{1}{2}\mathcal{G}'$ and $\mathbb{C} = \|u_t(t, \cdot)\|_2^2 + \int_{t_0}^t Q(\tau)\|u_\tau(\tau, \cdot)\|_2^2 d\tau + \beta$. Hence (5.5) holds now in $[t_0, t_0 + T_0]$, while (5.6) is valid in I . The fact that u cannot be global shows that also this case cannot occur. \square

Of course Theorem 5.5 extends and generalizes the second part of Theorem 4 of [23] and Theorem 3.1 of [24] when the damping is linear in v .

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